The Idea and Structures of Geometrodynamics

Domenico Giulini

Topics

The Idea and Structures of Geometrodynamics

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Clifford's dream GR 3-1 Hypersurface deformations Hamiltonian GR Connection Variables X without X Superspace Geometry Topology 3 manifolds Prime decomposition $\mathbb{R}R^{3}$ $\mathbb{R}P^{3}\mathbb{R}P^{3}$

William Kingdon Clifford 1870

"I wish here to indicate a manner in which these speculations may be applied to the investigation of physical phenomena. I hold in fact:

- 1. That small portions of space *are* in fact of a nature analogous to little hills on a surface which is on the average flat; namely, that the ordinary laws of geometry are not valid in them.
- 2. That this property of being curved or distorted is continually being passed from one portion of space to another after the manner of a wave.
- 3. That this variation of the curvature of space is what really happens in that phenomenon which we call the *motion of matter*, whether ponderable or etherial.
- 4. That in the physical world nothing else takes place but this variation, subject (possibly) to the law of continuity."

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"People slowly accustomed themselves to the idea that the physical states of space itself were the final physical reality." —PROFESSOR ALBERT EINITEIN

The New Youher

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Einstein's equation

 $R_{\mu
u}-rac{1}{2}R\,g_{\mu
u}+\Lambda\,g_{\mu
u}=\kappa T_{\mu
u}$

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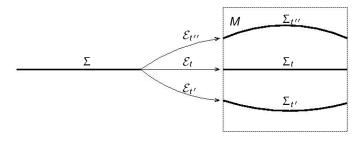
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Clifford's dream

GR

Hypersurface deformation: Hamiltonian GR Connection Variables X without X Superspace Geometry Topology 3 manifolds Prime decomposition $\mathbb{R}R^{p^3}$ $\mathbb{R}P^3 \mathbb{R}P^3$

Spacetime as space's history



Spacetime, *M*, is foliated by a one-parameter family of embeddings \mathcal{E}_t of the 3-manifold Σ into *M*. Σ_t is the image in *M* of Σ under \mathcal{E}_t .

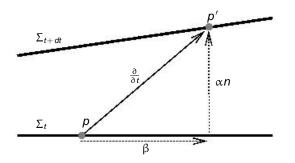
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A four-function worth of arbitrariness



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For $q \in \Sigma$ the image points $p = \mathcal{E}_t(q)$ and $p' = \mathcal{E}_{t+dt}(q)$ are connected by the vector $\partial/\partial t|_p$ whose components tangential and normal to Σ_t are β (three functions) and αn (one function) respectively.

Kinematics of hypersurface deformations

In local coordinates y^μ of M and x^m of Σ the generators of normal and tangential deformations of the embedded hypersurface are

$$N_{\alpha} = \int_{\Sigma} d^{3}x \, \alpha(x) \, n^{\mu}[y(x)] \, \frac{\delta}{\delta y^{\mu}(x)}$$
$$T_{\beta} = \int_{\Sigma} d^{3}x \, \beta^{m}(x) \, \partial_{m}y^{\mu}(x) \, \frac{\delta}{\delta y^{\mu}(x)}$$

This is merely the foliation-dependent decomposition of the tangent vector X(V) at y ∈ Emb(Σ, M), induced by the spacetime vector field V = α n + β^a∂_a:

$$X(V) = \int_{\Sigma} d^3x \ V^{\mu}(y(x)) \ \frac{\delta}{\delta y^{\mu}(x)}$$

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Topics Ciliford's dream GR 341 Hypersurface deformations Hamiltonian GR Connection Variables X without X Superspace Geometry Topology 3 manifolds Prime decomposition $\mathbb{R}RP^3$ $\mathbb{R}P^3 \mathbb{R}P^3$ • The vector fields X(V) on $\text{Emb}(\Sigma, M)$ obey

[X(V), X(W)] = X([V, W]),

i.e. $V \mapsto X(V)$ is a Lie homomorphism from the tangent-vector fields on *M* to the tangent-vector fields on Emb(Σ , *M*).

In terms of the normal-tangential decomposition:

$$\begin{split} [T_{\beta}, T_{\beta'}] &= -T_{[\beta,\beta']}, \\ [T_{\beta}, N_{\alpha}] &= -N_{\beta(\alpha)}, \\ [N_{\alpha}, N_{\alpha'}] &= -\epsilon T_{\alpha \operatorname{grad}_{h}(\alpha') - \alpha' \operatorname{grad}_{h}(\alpha)}, \end{split}$$

Here ∈ = 1 for Lorentzian and = −1 for Euclidean spacetimes, just to keep track of signature dependence. The Idea and Structures of Geometrodynamics

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Hamiltonian GR

- The idea is to represent the algebraic structure of hypersurface deformations in terms of a Hamiltonian dynamical system of physical fields.
- Theorem: The most general local realisation on the cotangent bundle over Riem(Σ), coordinatised by (h, π), is

$$\begin{split} & \mathcal{N}_{\alpha} \ \mapsto \mathcal{H}_{\alpha}[h,\pi] := \int_{\Sigma} \alpha(x) \, \mathcal{H}[h,\pi](x) \\ & \mathcal{T}_{\beta} \ \mapsto \mathcal{D}_{\beta}[h,\pi] := \int_{\Sigma} \beta^{a}(x) \, h_{ab}(x) \, \mathcal{D}^{b}[h,\pi](x) \end{split}$$

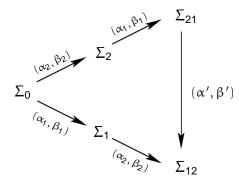
where

$$\begin{aligned} \mathcal{H}[h,\pi] &:= \varepsilon(2\kappa) G_{ab\,cd} \pi^{ab} \pi^{cd} - (2\kappa)^{-1} \sqrt{h} \left(R - 2\Lambda\right) \\ \mathcal{D}^{b}[h,\pi] &:= -2 \nabla_{a} \pi^{ab} \end{aligned}$$

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Successive hypersurface deformations parametrised by (α_1, β_1) and $N_2 = (\alpha_2, \beta_2)$ do not commute; rather

$$[X(\alpha_1,\beta_1), X(\alpha_2,\beta_2)] = X(\alpha',\beta'),$$

where

$$\begin{aligned} \alpha' &= \beta_1(\alpha_2) - \beta_2(\alpha_1) \,, \\ \beta' &= [\beta_1, \beta_2] + \alpha_1 \operatorname{grad}_h(\alpha_2) - \alpha_2 \operatorname{grad}_h(\alpha_1) \,. \end{aligned}$$

Since α' depends on h, we get the following condition for the Hamiltonians to act (via Poisson Bracket) as derivations on phase-space functions:

 $\{\{F, H(\alpha_1, \beta_1)\}, H(\alpha_2, \beta_2)\} - \{\{F, H(\alpha_2, \beta_2)\}, H(\alpha_1, \beta_1)\}$ = $\{F, \{H(\alpha_1, \beta_1), H(\alpha_2, \beta_2)\}\} = \{F, H(\alpha', \beta')\}$ = $\{F, H\}(\alpha', \beta') + H(\{F, \alpha'\}, \{F, \beta'\})$ $\stackrel{!}{=} \{F, H\}(\alpha', \beta')$

The last equality must hold for all *F* and all (α₁, β₁) (α₂, β₂). This implies the constraints:

 $\mathcal{H}[h,\pi](\mathbf{x}) = \mathbf{0}$ $\mathcal{D}^{\mathbf{a}}[h,\pi](\mathbf{x}) = \mathbf{0}$

- Constraints correspond to ⊥⊥ and ⊥ || components of Einstein's equation. A spacetime in which constraints are satisfied for each Σ must obey Einstein's equation.
- The constraints do not cause topological obstructions to Cauchy surface. Only special requirements do, like e.g. time-symmetry.

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Connection Variables

 The phase space of GR may be described by a (complex) SO(3) connection Aⁱ_a and a densitised 3-bein E^a_i, where

 $A_a^i := \Gamma_a^i + \beta K_a^i$, $\beta =$ Immirzi parameter.

The Hamiltonian constraint reads:

$$\begin{split} \varepsilon^{ijk} \tilde{E}^a_i \tilde{E}^b_j \, F_{ab\,k} \\ - 2(1+\beta^{-2}) \, \tilde{E}^a_{[i} \tilde{E}^b_{j]} \left(A^i_a - \Gamma^i_a \right) \left(A^j_b - \Gamma^j_b \right) = 0 \,. \end{split}$$

Unless β = i the connection Aⁱ_a cannot be thought of as restriction to space of a spacetime connection. For example, its holonomy along a spacelike curve γ in spacetime depends on the choice of Σ ⊃ γ.

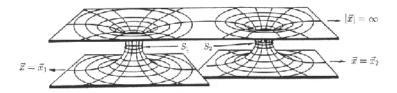
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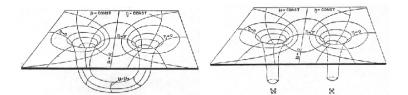
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Topologies for two BHs





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Mass without mass

The mass-energy of an asymptotically flat end is

$$m \propto \lim_{R \to \infty} \left\{ \int_{S^2_R \subset \Sigma} d\sigma (\partial_a h_{ab} - \partial_b h_{aa}) n^b \right\}$$

- This is ≥ 0 and = 0 for Minkowski slices only.
- Gannon's theorem implies causal geodesic incompleteness if π₁(Σ) ≠ 1 (replacing ∃ trapped surfaces in the hypotheses).
- Stationary regular vacuum solutions (gravitational solitons) do not exist (Einstein & Pauli, Lichnerowicz).

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Momenta without momenta

 The linear and angular momenta of an asymptotically flat end is

$$p^a \propto \int_{S^2_{\infty}} d\sigma \, \pi^{ab} n_b \,, \qquad J^a \propto \int_{S^2_{\infty}} d\sigma \, \varepsilon_{abc} \, x^b \pi^{cd} n_d$$

Axisymmetric vacuum configurations with J ≠ 0 and one end do not exist, even for non-orientable Σ:

$$J_{K} = \int_{S_{\infty}^{2}} \star dK = \int_{\Sigma} \underbrace{d \star dK}_{\propto \mathsf{Ric}} = 0$$

 But for Killing fields K up to sign they do (Friedman & Mayer 1981). The Idea and Structures of Geometrodynamics

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Charge without charge

Electrovac solutions with non-zero overall electric charge

 $Q_e = \int_{\mathcal{S}^2_{\infty}} \star F$

only exist if $S_{\infty}^2 \neq \partial \Sigma$, i.e. if $[S_{\infty}^2] \in H^2(\Sigma)$ is non-trivial, like e.g. in Reissner-Nordström.

If Σ has only one end and is non-orientable, Stokes' theorem obstructs existence of electric but not of magnetic charge (Sorkin 1977):

$$Q_m = \int_{S^2_{\infty}} F$$

 This is because for non-orientable Σ, Stokes' theorem holds for twisted (densitised) but not for ordinary forms. The Idea and Structures of Geometrodynamics

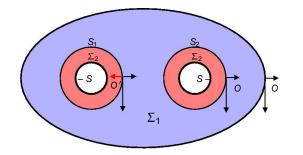
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- ► Stokes' theorem applied to $\vec{\nabla} \cdot \vec{B} = 0$ in Σ_1 : $\Phi(\vec{B}, \partial \Sigma_1, O) + \Phi(\vec{B}, S_1, O) + \Phi(\vec{B}, S_2, O) = 0$
- ► Stokes' theorem applied to $\vec{\nabla} \cdot \vec{B} = 0$ in Σ_2 : $\Phi(\vec{B}, S_1, O') + \Phi(\vec{B}, S_2, O) = 0$

Hence

 $\Phi(\vec{B}, \partial \Sigma_1, O) = -2 \, \Phi(\vec{B}, S_1, O) \neq 0$

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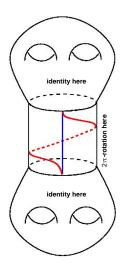
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Spin without spin

- There exist many 3-manifolds for which a full (i.e. 2π) relative rotation is not in the id-component.
- In this case the asymptotic symmetry group at spacelike infinity contains SU(2) rather than SO(3).
- This has been suggested as a 'fermions-from-bosons' mechanism in gravity (Friedman & Sorkin 1982).
- The spinoriality-status of each known 3-manifold is also known.



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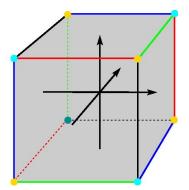
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Example: The space form S^3/D_8^*



- $\Sigma = S^3/D_8^*$ is spinorial
- $\blacktriangleright D_8^* = \langle a, b \mid a^2 = b^2 = (ab)^2 \rangle$
- $MCG_{\infty}(\Sigma) \cong Aut(D_8^*) \cong O$
- $MCG_{F}(\Sigma) \cong Aut_{\mathbb{Z}_{2}}(D_{8}^{*}) \cong O^{*}$
- This manifold is also chiral, i.e. it admits no orientation-reversing self-diffeomorphism (like many other 3-manifolds)

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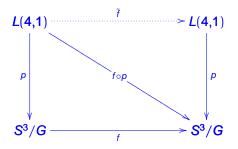
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Chirality of spherical space-forms



 $\deg(\tilde{f}) \cdot \deg(p) = \deg(p) \cdot \deg(f)$

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Superspace

 $Riem(\Sigma)$. . $\pi_1 \cong MCG_F(\Sigma)$ The Idea and Structures of Geometrodynamics

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Geometry

 The group Diff_F(Σ) acts as isometries on the Wheeler-DeWitt metric on Riem(Σ)

$$\mathcal{G}_h(k,\ell) := \int_{\Sigma} d^3x \; G^{ab\,cd}[h](x) \; k_{ab}(x) \, \ell_{cd}(x) \, .$$

Hence *G* defines a metric on superspace in the usual way iff horizontal lifts are unique.

Now, the vertical subspace at h ∈ Riem(Σ) is spanned by all vectors of the form

$$X^{\xi} = \int_{\Sigma} d^3x \, L_{\xi} h_{ab} \, \frac{\delta}{\delta h_{ab}} \,, \quad \forall \xi \,.$$

Hence $k \in T_h \operatorname{Riem}(\Sigma)$ is horizontal (*G*-orthogonal to all vertical vectors) iff

$$\mathcal{O}_h k = 0 \Leftrightarrow \nabla^b (k_{ab} - \lambda h_{ab} k_c^c) = 0$$

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 $(\delta d + 2(1 - \lambda)d\delta - 2\operatorname{Ric}) \xi = -\mathcal{O}_h k$.

- Killing fields ∈ kernel of the l.h.s. operator (symmetric) and right hand side is L²-orthogonal to Killing fields. Non-Killing ξ in the kernel correspond precisely to those non-zero X^ξ that form the non-trivial intersection of the vertical and horizontal subspace of *T_h*Riem(Σ), which exist for *G* non-pos. def. (λ > 1/3).
- Example: ξ = dφ generate inf. dim. intersection at (locally) flat metrics in case λ = 1, whereas no non-trivial intersection exists at Ric < 0 metrics, which always exist, and at non-flat Einstein metrics (space forms).
- The symbol of the l.h.s. operator is

 $\sigma(\zeta)_b^a = \|\zeta\|^2 \left(\delta_b^a + (1-2\lambda)\zeta^a \zeta_b / \|\zeta\|^2\right) \,,$

which is elliptic for $\lambda \neq 1$ (strongly for $\lambda > 1$) and degenerate for the GR case $\lambda = 1$.

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- ► Let now $\lambda = 1$ (GR value). Since then \mathcal{G} defines a metric at points $[h] \in \mathcal{S}(\Sigma)$ where *h* is Einstein, it does so for the round metric on $\Sigma = S^3$.
- We ask: What is the signature (n_−, n₊) of the metric that G defines in T_[h] ∈ S(Σ)? The answer is given by the following

Theorem

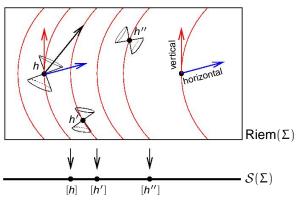
The Wheeler–DeWitt metric in a neighbourhood of the round 3-sphere in $S(\Sigma)$ is of signature $(-1, \infty)$, that is, it is an infinite-dimensional Lorentzian metric. (DG 1995)

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Topology

- MCG of 3-manifolds are the π₁ of corresponding superspace. They are topological but *not* homotopy invariants.
- ► Consider 'lens spaces' $L(p,q) =: S^3 / \sim$, where q < p are coprime integers, with $S^3 = \{|z_1|^2 + |z_1|^2 = 1 \mid (z_1, z_2) \in \mathbb{C}^2\}$ and $(z_1, z_2) \sim (z'_1, z'_2) \Leftrightarrow z'_1 = \exp(2\pi i/p)z_1$ and $z'_2 = \exp(2\pi iq/p)z_2$.
- Have homotopy (≃) and topological (≅) equivalence properties (Whitehead 1941, Reidemeister 1935):

 $egin{aligned} L(p,q) &\simeq L(p,q') \ \Leftrightarrow \ q'q = \pm n^2 \ (ext{mod } p) \ L(p,q) &\cong L(p,q') \ \Leftrightarrow \ q' = \pm q^{\pm 1} \ (ext{mod } p) \ [q'=q^{\pm 1} \ ext{for } o.p.] \end{aligned}$

For p > 2 have:

 $\mathrm{MCG}_{\mathcal{F}}(L(p,q)) = \begin{cases} \mathbb{Z}_2 \times \mathbb{Z}_2 & \text{if } q^2 = 1 \pmod{p} \text{ and } q \neq \pm 1 \pmod{p} \\ \mathbb{Z}_2 & \text{otherwise} \end{cases}$

▶ For example, $L(15, 1) \simeq L(15, 4)$ and $L(15, 1) \not\cong L(15, 4)$, but

 $\mathrm{MCG}_{\mathsf{F}}(L(15,1)) = \mathbb{Z}_2 \neq \mathbb{Z}_2 \times \mathbb{Z}_2 = \mathrm{MCG}_{\mathsf{F}}(L(15,4))$

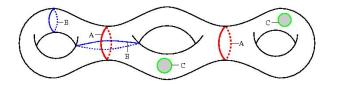
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Connected sums



- Decompose along *splitting* and *essential* 2-spheres until only *prime-manifolds* remain. Prime factors are unique up to permutation.
- Except for S¹ × S², a prime manifold has trivial π₂. The converse is true given PC. Given TGC, all finite-π₁ primes are spherical space-forms S³/G, G ⊂ SO(4). Infinite-π₁ primes are S¹ × S², the flat ones ℝ³/G, G ⊂ E₃, and the huge family of locally hyperbolic ones.

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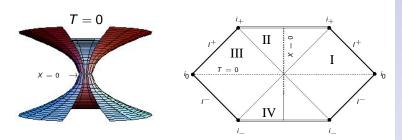
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The $\mathbb{R}P^3$ geon

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Clifford's dream GR 3+1 Hypersurface deformation Hamiltonian GR Connection Variables X without X Superspace Geometry Topology 3 manifolds Prime decomposition **ERP³ RP³ RP³ RP³**

 $(T, X, \theta, \phi) \mapsto (T, -X, \pi - \theta, \phi + \pi)$

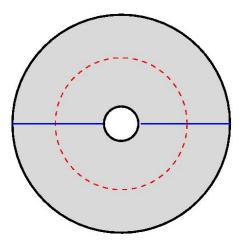
$\mathbb{R}P^3 \# \mathbb{R}P^3$

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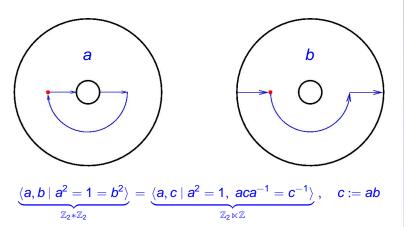
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Prime table



Its fundamental group



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MCG and its u.i. representations

The group of mapping classes is given by

$$\begin{split} \mathrm{MCG}_{\mathsf{F}} &\cong \mathrm{Aut}(\mathbb{Z}_2 \ast \mathbb{Z}_2) \cong \mathbb{Z}_2 \ast \mathbb{Z}_2 = \langle \mathsf{E}, \mathsf{S} \mid \mathsf{E}^2, \mathsf{S}^2 \rangle \\ & \mathsf{E} : (\mathsf{a}, \mathsf{b}) \to (\mathsf{b}, \mathsf{a}), \quad \mathsf{S} : (\mathsf{a}, \mathsf{b}) \to (\mathsf{a}, \mathsf{a}\mathsf{b}\mathsf{a}^{-1}) \end{split}$$

- $\Rightarrow ES + SE \subset \text{centre of group algebra. Hence } \{1, E, S, ES\}$ generate algebra of irreducible representing operators.
- ⇒ Linear irreducible representations are at most 2-dimensional. They are: $E \mapsto \pm 1$, $S \mapsto \pm 1$ and, for $0 < \theta < \pi$,

$$egin{array}{lll} E\mapsto \left(egin{array}{cc} 1&0\0&-1\end{array}
ight) \ S\mapsto \left(egin{array}{cc} \cos heta&\sin heta\ \sin heta&-\cos heta\end{array}
ight), \end{array}$$

⇒ There are two 'statistics sectors', which get 'mixed' by S; the 'mixing angle' is θ.

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Colico: Clifford's dream GR 3+1 Hypersurface deformations Hamiltonian GR Connection Variables X without X Superspace Geometry Topology 3 manifolds Prime decomposition $\mathbb{R}R^{p^2}$ $\mathbb{R}P^2 \# \mathbb{R}P^2$ Prime table

Prime II	$_{\rm HC}$	\mathbf{S}	С	Ν	$H_1(\Pi)$	$\pi_0(D_F(\Pi))$	$\pi_1(D_F(\Pi))$	$\pi_k(D_F(\Pi))$
S^{3}/D_{8}^{*}	+	+	+	-	$Z_2 \times Z_2$	O*	0	$\pi_k(S^3)$
S^{3}/D_{8n}^{*}	+	$^+$	+	-	$Z_2 \times Z_2$	D_{16n}^{*}	0	$\pi_k(S^3)$
$S^3/D^*_{4(2n+1)}$	+	+	+	÷	Z_4	$D^{*}_{8(2n+1)}$	0	$\pi_k(S^3)$
S^{3}/T^{*}	?	+	+	-	Z_3	0*	0	$\pi_k(S^3)$
S^{3}/O^{*}	w	$^+$	+	+	Z_2	0*	0	$\pi_k(S^3)$
S^{3}/I^{*}	?	+	+	-	0	I^*	0	$\pi_k(S^3)$
$S^3/D_8^* \times Z_p$	+	+	+	-	$Z_2 \times Z_{2p}$	$Z_2 \times O^*$	Z	$\pi_k(S^3)\times\pi_k(S^3)$
$S^3/D^*_{8n} \times Z_p$	+	+	+	-	$Z_2 \times Z_{2p}$	$Z_2 \times D^*_{16n}$	Z	$\pi_k(S^3)\times\pi_k(S^3)$
$S^3/D^*_{4(2n+1)} \times Z_p$	+	+	+	+	Z_{4p}	$Z_2 \times D^*_{8(2n+1)}$	Z	$\pi_k(S^3)\times\pi_k(S^3)$
$S^3/T^* \times Z_p$?	+	+	-	Z_{3p}	$Z_2 \times O^*$	Z	$\pi_k(S^3)\times\pi_k(S^3)$
$S^3/O^* \times Z_p$	w	+	+	+	Z_{2p}	$Z_2 \times O^*$	Z	$\pi_k(S^3)\times\pi_k(S^3)$
$S^3/I^* \times Z_p$?	+	+	-	Z_p	$Z_2 \times I^*$	Z	$\pi_k(S^3)\times\pi_k(S^3)$
$S^{3}/D'_{2^{k}(2n+1)} \times Z_{p}$	+	+	+	+	$Z_p \times Z_{2^k}$	$Z_2 \times D^*_{8(2n+1)}$	Z	$\pi_k(S^3)\times\pi_k(S^3)$
$S^3/T'_{8\cdot 3^m} \times Z_p$?	+	+	-	$Z_p \times Z_{3^m}$	O*	Z	$\pi_k(S^3)\times\pi_k(S^3)$
$L(p, q_1)$	w	-	+	$(-)^p$	Z_p	Z_2	Ζ	$\pi_k(S^3)$
$L(p, q_2)$	w+	-	+	$(-)^p$	Z_p	$Z_2 \times Z_2$	$Z \times Z$	$\pi_k(S^3) \times \pi_k(S^3)$
$L(p, q_{3})$	w	-	-	$(-)^p$	Z_p	Z_2	$Z \times Z$	$\pi_k(S^3) \times \pi_k(S^3)$
$L(p, q_4)$	w	-	+	$(-)^p$	Z_p	Z_2	$Z \times Z$	$\pi_k(S^3) \times \pi_k(S^3)$
RP^3	+	-	-	+	Z_2	1	0	0
S^3	+	-	-	-	1	1	0	0
$S^2 \times S^1$	/	-	-	+	Z	$Z_2 \times Z_2$	Z	$\pi_k(S^3)\times\pi_k(S^2)$
R^{3}/G_{1}	/	+	-	+	$Z\times Z\times Z$	St(3, Z)	0	$\pi_k(S^3)$
R^{3}/G_{2}	1	+	-	÷	$Z\times Z_2\times Z_2$	$\operatorname{Aut}_{+}^{\mathbb{Z}_2}(G_2)$	0	$\pi_k(S^3)$
R^{3}/G_{3}	/	+	+	+	$Z \times Z_3$	$\operatorname{Aut}_{+}^{\mathbb{Z}_2}(G_3)$	0	$\pi_k(S^3)$
R^{3}/G_{4}	/	+	+	-	$Z \times Z_2$	$\operatorname{Aut}_{+}^{\mathbb{Z}_2}(G_4)$	0	$\pi_k(S^3)$
R^{3}/G_{5}	1	+	+	+	Z	$Aut_{+}^{Z_{2}}(G_{5})$	0	$\pi_k(S^3)$
R^{3}/G_{6}	1	+	+	-	$Z_4 \times Z_4$	$Aut_{+}^{Z_{2}}(G_{5})$	0	$\pi_k(S^3)$
$S^1 \times R_g$	/	+	-	-	$Z \times Z_{2g}$	$\operatorname{Aut}_{+}^{\mathbb{Z}_2}(\mathbb{Z} \times F_g)$	0	$\pi_k(S^3)$
$K(\pi, 1)_{sl}$	/	+	*	*	$A\pi$	$Aut_{\perp}^{Z_2}(\pi)$	0	$\pi_{k}(S^{3})$

The Idea and Structures of Geometrodynamics

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Topics Clifford's dream GR 3+1 Hypersurface deformatione Hamiltonian GR Connection Variables X without X Superspace Geometry Topology 3 manifolds Prime decomposition RCP³ RCP³

Prime table

taken from D.G. 1996