

Lecture 7

Einstein's field equation relate tensors ( $R_{\alpha\beta}$ ,  $T_{\alpha\beta}$  etc.) pointwise on a 4-dim. manifold  $M$  with Lorentz metric  $g$ ; the equations are "local".

We recall the transformation property of tensors: Let  $T \in ST_m^l(M)$ , i.e.

$$T = T_{\beta_1 \dots \beta_m}^{\alpha_1 \dots \alpha_l} \frac{\partial}{\partial x^{\alpha_1}} \otimes \dots \otimes \frac{\partial}{\partial x^{\alpha_l}} \otimes dx^{\beta_1} \otimes \dots \otimes dx^{\beta_m} \quad (7.1)$$

Then, if  $\bar{x}^\alpha = \bar{x}^\alpha(x)$  and  $x^\alpha = X^\alpha(\bar{x})$  are the chart transition maps

$$\left. \begin{aligned} \frac{\partial}{\partial x^\alpha} &= \frac{\partial \bar{x}^\delta}{\partial x^\alpha} \frac{\partial}{\partial \bar{x}^\delta} \\ dx^\beta &= \frac{\partial X^\beta}{\partial \bar{x}^\delta} d\bar{x}^\delta \end{aligned} \right\} (7.2)$$

so that

$$T = \bar{T}_{\delta_1 \dots \delta_m}^{\gamma_1 \dots \gamma_l} \frac{\partial}{\partial \bar{x}^{\gamma_1}} \otimes \dots \otimes \frac{\partial}{\partial \bar{x}^{\gamma_l}} \otimes d\bar{x}^{\delta_1} \otimes \dots \otimes d\bar{x}^{\delta_m} \quad (7.3)$$

where

$$\bar{T}_{\delta_1 \dots \delta_m}^{\gamma_1 \dots \gamma_l}(\bar{x}) = T_{\beta_1 \dots \beta_m}^{\alpha_1 \dots \alpha_l}(x) \frac{\partial \bar{x}^{\gamma_1}}{\partial x^{\alpha_1}} \dots \frac{\partial \bar{x}^{\gamma_l}}{\partial x^{\alpha_l}} \times \frac{\partial X^{\beta_1}}{\partial \bar{x}^{\delta_1}} \dots \frac{\partial X^{\beta_m}}{\partial \bar{x}^{\delta_m}} \quad (7.4)$$

Many of the geometric quantities we consider involve the Christoffel-symbols

$$\Gamma_{\alpha\beta}^{\lambda} := \frac{1}{2} g^{\lambda\sigma} (-g_{\alpha\beta,\sigma} + g_{\sigma\alpha,\beta} + g_{\beta\sigma,\alpha}) \quad (7.5)$$

(as usual we write  $g_{\alpha\beta,\sigma} = \partial_{\sigma} g_{\alpha\beta} = \partial g_{\alpha\beta} / \partial x^{\sigma}$ ), which we encountered in the geodesic eqn.

$$\ddot{z}^{\lambda} + \Gamma_{\alpha\beta}^{\lambda} \dot{z}^{\alpha} \dot{z}^{\beta} = 0. \quad (7.6)$$

The Christoffel symbols represent a geometric object (a connection) which is not a tensor on  $M$ . To see how the coefficients  $\Gamma_{\alpha\beta}^{\lambda}$  behave under changes of charts we rewrite (7.6) in terms of coordinates  $\bar{X}$ :

$$\left. \begin{aligned} \bar{z}^{\lambda} &= \bar{X}^{\lambda} \circ \gamma = (\bar{\phi} \circ \phi^{-1})^{\lambda}(\bar{z}) \\ z^{\lambda} &= X^{\lambda} \circ \gamma = (\phi \circ \bar{\phi}^{-1})^{\lambda}(\bar{z}) \end{aligned} \right\} (7.7)$$

Then

$$\left. \begin{aligned} \dot{z}^{\lambda} &= \frac{\partial X^{\lambda}}{\partial \bar{X}^{\sigma}} \dot{\bar{z}}^{\sigma} \\ \ddot{z}^{\lambda} &= \frac{\partial X^{\lambda}}{\partial \bar{X}^{\sigma}} \ddot{\bar{z}}^{\sigma} + \frac{\partial^2 X^{\lambda}}{\partial \bar{X}^{\mu} \partial \bar{X}^{\nu}} \dot{\bar{z}}^{\mu} \dot{\bar{z}}^{\nu} \end{aligned} \right\} (7.8)$$

and (7.6) turns into

$$\frac{\partial X^{\lambda}}{\partial \bar{X}^{\sigma}} \ddot{\bar{z}}^{\sigma} + \left( \Gamma_{\alpha\beta}^{\lambda} \frac{\partial X^{\alpha}}{\partial \bar{X}^{\mu}} \frac{\partial X^{\beta}}{\partial \bar{X}^{\nu}} + \frac{\partial^2 X^{\lambda}}{\partial \bar{X}^{\mu} \partial \bar{X}^{\nu}} \right) \dot{\bar{z}}^{\mu} \dot{\bar{z}}^{\nu} = 0 \quad (7.9)$$

or equivalently

$$\ddot{\bar{x}}^\sigma + \left( \frac{\partial \bar{x}^\sigma}{\partial x^\lambda} \Gamma_{\alpha\beta}^\lambda \frac{\partial x^\alpha}{\partial \bar{x}^\mu} \frac{\partial x^\beta}{\partial \bar{x}^\nu} + \frac{\partial \bar{x}^\sigma}{\partial x^\lambda} \frac{\partial^2 x^\lambda}{\partial \bar{x}^\mu \partial \bar{x}^\nu} \right) \dot{\bar{x}}^\mu \dot{\bar{x}}^\nu = 0 \quad (7.10)$$

But this must equal the geodesic equation in  $\bar{x}$  coordinates

$$\ddot{\bar{x}}^\sigma + \bar{\Gamma}_{\mu\nu}^\sigma \dot{\bar{x}}^\mu \dot{\bar{x}}^\nu = 0$$

hence

$$\bar{\Gamma}_{\mu\nu}^\sigma = \underbrace{\Gamma_{\alpha\beta}^\lambda \frac{\partial \bar{x}^\sigma}{\partial x^\lambda} \frac{\partial x^\alpha}{\partial \bar{x}^\mu} \frac{\partial x^\beta}{\partial \bar{x}^\nu}}_{\text{homogeneous part (like a tensor)}} + \underbrace{\frac{\partial \bar{x}^\sigma}{\partial x^\lambda} \frac{\partial^2 x^\lambda}{\partial \bar{x}^\mu \partial \bar{x}^\nu}}_{\text{inhomogeneous part}} \quad (7.11)$$

Note:  $\frac{\partial \bar{x}^\sigma}{\partial x^\lambda} \frac{\partial}{\partial \bar{x}^\mu} \frac{\partial x^\lambda}{\partial \bar{x}^\nu}$

$$= - \frac{\partial^2 \bar{x}^\sigma}{\partial x^\lambda \partial x^s} \frac{\partial x^s}{\partial \bar{x}^\mu} \frac{\partial x^\lambda}{\partial \bar{x}^\nu}$$

$$= - \frac{\partial^2 \bar{x}^\sigma}{\partial x^\lambda \partial x^\beta} \frac{\partial x^\lambda}{\partial \bar{x}^\mu} \frac{\partial x^\beta}{\partial \bar{x}^\nu} \quad (7.12)$$

This allows to write (7.11) in a more convenient form

$$\bar{\Gamma}_{\mu\nu}^{\sigma} = \frac{\partial \bar{X}^{\sigma}}{\partial X^{\lambda}} \frac{\partial X^{\lambda}}{\partial \bar{X}^{\mu}} \frac{\partial X^{\beta}}{\partial \bar{X}^{\nu}} \left( \Gamma_{\alpha\beta}^{\lambda} - \frac{\partial X^{\lambda}}{\partial \bar{X}^{\sigma}} \frac{\partial^2 \bar{X}^{\sigma}}{\partial X^{\alpha} \partial X^{\beta}} \right) \quad (7.13)$$

This differs from (7.11) just in the way we write the inhomogeneous part.

Note: In differential geometry a geometric object is characterised by a definite transformation property of the coefficients which represent it. A tensor has a linear homogeneous transformation law, but that is not a necessary condition for the qualification as a geometric object. The Christoffel symbols, too, represent a geometric object — the Levi-Civita connection.

Let  $p \in M$  be a fixed point and  $X^{\lambda}$  the coordinates in a neighbourhood  $\mathcal{U}$  of  $p$ . Consider the following coordinate transformation in  $\mathcal{U}$

$$\begin{aligned} \bar{X}^{\lambda}(q) &:= X^{\lambda}(q) - X^{\lambda}(p) \\ &+ \frac{1}{2} \Gamma_{\alpha\beta}^{\lambda}(p) (X^{\alpha}(q) - X^{\alpha}(p))(X^{\beta}(q) - X^{\beta}(p)) \end{aligned} \quad (7.14)$$

Then

$$\left. \frac{\partial \bar{X}^{\lambda}}{\partial X^{\sigma}} \right|_p = \delta_{\sigma}^{\lambda}, \quad \left. \frac{\partial^2 \bar{X}^{\sigma}}{\partial X^{\alpha} \partial X^{\beta}} \right|_p = \Gamma_{\alpha\beta}^{\sigma}(p) \quad (7.15)$$

Equation (7.13) then immediately gives

$$\Gamma_{\mu\nu}^{\sigma}(p) = 0 \quad (7.16)$$

In addition, we may always achieve

$$\left. \begin{aligned} g_{\alpha\beta}(p) &= g\left(\frac{\partial}{\partial \bar{x}^{\alpha}}, \frac{\partial}{\partial \bar{x}^{\beta}}\right)\Big|_p \\ &= \eta_{\alpha\beta} = \text{diag}(1, -1, -1, -1). \end{aligned} \right\} (7.17)$$

[This can be achieved by a linear transformation  $\bar{x}^{\alpha} \mapsto \bar{X}^{\alpha} = \Lambda^{\alpha}_{\beta} \bar{x}^{\beta}$  under which the  $\Gamma$ 's transform linear-homogeneously and therefore stay zero once they are zero.]

Proposition and Definition. For any point  $p \in M$  there exists a chart  $(\mathcal{U}, \phi)$  with  $p \in \mathcal{U}$ ,  $\phi: \mathcal{U} \rightarrow \mathbb{R}^n$ ,  $\phi = x^{\alpha} e_{\alpha}$ ,  $x^{\alpha}: \mathcal{U} \rightarrow \mathbb{R}$  coord. functions, with

$$\left. \begin{aligned} x^{\alpha}(p)' &= 0, \quad g_{\alpha\beta}(p) = \eta_{\alpha\beta} \\ g_{\alpha\beta,\gamma}(p) &= 0 \end{aligned} \right\} (7.18)$$

Such a chart is called a Riemannian Normal coordinate system at  $p$ .

Note that

$$g_{\alpha\beta,\gamma}(p) = 0 \Leftrightarrow \Gamma_{\alpha\beta}^{\lambda}(p) = 0$$

In fact, the first derivatives of  $g$  and  $\Gamma$  are just related by linear invertible maps:

$$\Gamma_{\alpha\beta}^{\lambda} = \frac{1}{2} g^{\lambda\sigma} (-g_{\alpha\beta,\sigma} + g_{\sigma\alpha,\beta} + g_{\beta\sigma,\alpha}) \quad (7.19)$$

Since  $\Gamma_{\alpha\beta}^{\lambda} = \Gamma_{\beta\alpha}^{\lambda}$  there are

$$\frac{1}{2} n(n+1) \cdot n$$

$$= 40 \quad \text{for } n=4$$

independent components in  $n$  dimensions, just like  $g_{\alpha\beta,\gamma} = g_{\beta\alpha,\gamma}$ .

From (7.19)

$$\begin{aligned} g^{\lambda\sigma} \Gamma_{\alpha\beta}^{\lambda} &= \frac{1}{2} (-g_{\alpha\beta,\sigma} + g_{\sigma\alpha,\beta} + g_{\beta\sigma,\alpha}) \\ + g^{\lambda\alpha} \Gamma_{\sigma\beta}^{\lambda} &= \frac{1}{2} (-g_{\sigma\beta,\alpha} + g_{\alpha\sigma,\beta} + g_{\beta\alpha,\sigma}) \end{aligned}$$

$$\Rightarrow g_{\alpha\sigma,\beta} = g^{\lambda\alpha} \Gamma_{\sigma\beta}^{\lambda} + g^{\lambda\sigma} \Gamma_{\alpha\beta}^{\lambda} \quad (7.20)$$

The  $\Gamma$ -symbols are just the coefficients of a covariant derivative

$$\nabla_{\frac{\partial}{\partial x^\alpha}} \left( \frac{\partial}{\partial x^\beta} \right) = \Gamma_{\alpha\beta}^\lambda \frac{\partial}{\partial x^\lambda} \quad (7.21)$$

$$\nabla_{\frac{\partial}{\partial x^\alpha}} (dx^\beta) = -\Gamma_{\alpha\lambda}^\beta dx^\lambda \quad (7.22)$$

Here  $\nabla$  is a map

$$\nabla : ST_m^l(M) \rightarrow ST_{m+1}^l(M)$$

$$\text{or } \nabla : ST_0^1(M) \times ST_m^l(M) \rightarrow ST_m^l(M)$$

$$(X, T) \mapsto \nabla_X T$$

satisfying  $(\forall f \in C^\infty(M), X \in ST_0^1(M), T \in ST_m^l(M))$ :

$$\nabla_X f = X(f)$$

$$T \mapsto \nabla_X T \text{ is } \mathbb{R}\text{-linear}$$

$$X \mapsto \nabla_X T \text{ is } C^\infty(M)\text{-linear}$$

$$\nabla_X (T \otimes T') = \nabla_X T \otimes T' + T \otimes \nabla_X T'$$

$$C \circ \nabla_X = \nabla_X \circ C \quad (C = \text{contraction}).$$

The Levi-Civita connection is characterized by 7

1.) vanishing Torsion  $T \in ST_2^1(M)$

$$T(X, Y) := \nabla_X Y - \nabla_Y X - [X, Y] = 0 \quad (7.24)$$

2.) metricity

$$\nabla_X g = 0 \quad (7.25)$$

Then  $\nabla$  is uniquely determined

$$\begin{aligned} + \nabla_X (g(Y, Z)) &= \underbrace{g(\nabla_X Y, Z)}_1 + \underbrace{g(Y, \nabla_X Z)}_2 \\ + \nabla_Y (g(Z, X)) &= \underbrace{g(\nabla_Y Z, X)}_3 + \underbrace{g(Z, \nabla_Y X)}_1 \\ - \nabla_Z (g(X, Y)) &= \underbrace{g(\nabla_Z X, Y)}_2 + \underbrace{g(X, \nabla_Z Y)}_3 \end{aligned} \quad (7.26)$$

$$X(g(Y, Z)) + Y(g(Z, X)) - Z(g(X, Y))$$

$$= g(\nabla_X Y, Z) + g(\nabla_Y X, Z)$$

$$+ g(\nabla_X Z - \nabla_Z X, Y) + g(X, \nabla_Y Z - \nabla_Z Y)$$

$$= 2 g(\nabla_X Y, Z)$$

$$+ g([Y, X], Z) + g([X, Z], Y) + g([Y, Z], X)$$

(7.27)

where we used  $T = 0$ .



Hence

$$\begin{aligned}
 & g(\nabla \times y, z) \\
 &= \frac{1}{2} \left\{ (-z(g(x, y)) + x(g(y, z)) + y(g(z, x))) \right. \\
 &+ \left. g([x, y], z) - g([y, z], x) + g([z, x], y) \right\} \quad (7.28)
 \end{aligned}$$

If  $\{e_\alpha : \alpha = 0, 1, 2, 3\}$  are local basis fields, so that

$$[e_\alpha, e_\beta] = C_{\alpha\beta}^\gamma e_\gamma \quad (7.29)$$

and

$$\nabla_{e_\alpha} e_\beta = W_{\alpha\beta}^\gamma e_\gamma \quad (7.30)$$

$$g(e_\alpha, e_\beta) = g_{\alpha\beta} \quad (7.31)$$

Then, for  $X = e_\alpha, Y = e_\beta, Z = e_\gamma$ , (7.28) becomes

$$\begin{aligned}
 & W_{\alpha\beta}^\gamma g_{\gamma\delta} \\
 &= \frac{1}{2} \left( -e_\gamma(g_{\alpha\beta}) + e_\alpha(g_{\beta\gamma}) + e_\beta(g_{\gamma\alpha}) \right) \\
 &+ C_{\alpha\beta}^\gamma g_{\gamma\delta} - C_{\beta\gamma}^\alpha g_{\gamma\delta} + C_{\gamma\alpha}^\beta g_{\gamma\delta}
 \end{aligned}$$

Multiplication with  $g^{\sigma\lambda}$  gives

$$W_{\alpha\beta}^{\sigma} = \frac{1}{2} g^{\sigma\lambda} (-e_{\lambda}(g_{\alpha\beta}) + e_{\alpha}(g_{\beta\lambda}) + e_{\beta}(g_{\lambda\alpha})) \\ + \frac{1}{2} (C_{\alpha\beta}^{\sigma} - g^{\sigma\lambda} C_{\beta\lambda\alpha}^{\lambda} + g^{\sigma\lambda} C_{\lambda\alpha\beta}^{\lambda}) \quad (7.32)$$

The right-hand side is completely determined once  $g$  and the basis is specified. Hence the coefficients  $W_{\alpha\beta}^{\sigma}$  are uniquely determined and hence  $\nabla$  is.

In a coordinate basis  $e_{\alpha} = \frac{\partial}{\partial x^{\alpha}}$  we have  $C_{\alpha\beta}^{\gamma} = 0$  and

$$W_{\alpha\beta}^{\sigma} = \Gamma_{\alpha\beta}^{\sigma} \quad (7.33)$$

$\Rightarrow$  The Christoffel symbols are the coefficients of the unique cov. derivative with  $T=0$ ,  $\nabla g=0$  with respect to a chart basis field  $\frac{\partial}{\partial x^{\alpha}}$ .

Examples:  $X = X^{\alpha} \frac{\partial}{\partial x^{\alpha}}$ ,  $\nabla_X T = ?$

$$a) T = y = y^{\beta} \frac{\partial}{\partial x^{\beta}} \quad (\text{Vector field})$$

$$\Rightarrow \nabla_X y = \nabla_{X^{\alpha} \frac{\partial}{\partial x^{\alpha}}} (y^{\beta} \frac{\partial}{\partial x^{\beta}}) = X^{\alpha} \frac{\partial y^{\beta}}{\partial x^{\alpha}} \frac{\partial}{\partial x^{\beta}} \\ + X^{\alpha} y^{\beta} \Gamma_{\alpha\beta}^{\gamma} \frac{\partial}{\partial x^{\gamma}} = X^{\alpha} (y^{\gamma}_{,\alpha} + \Gamma_{\alpha\beta}^{\gamma} y^{\beta}) \frac{\partial}{\partial x^{\gamma}}$$

We write

$$\nabla \frac{\partial}{\partial x^\alpha} (y) = : (\nabla_\alpha y^\delta) \frac{\partial}{\partial x^\delta} \quad (7.34)$$

so that

$$\nabla_\alpha y = X^\alpha (\nabla_\alpha y^\delta) \frac{\partial}{\partial x^\delta} \quad (7.35)$$

then

$$\nabla_\alpha y^\delta = y^\delta_{,\alpha} + \Gamma_{\alpha\beta}^\delta y^\beta \quad (7.36)$$

b)  $T = \alpha = \alpha_\beta dx^\beta$  (co-vector field)

$$\begin{aligned} \nabla_\alpha \alpha &= \nabla_\alpha X^\beta \frac{\partial}{\partial x^\alpha} (\alpha_\beta dx^\beta) = X^\alpha \left( \frac{\partial \alpha_\beta}{\partial x^\alpha} dx^\beta \right. \\ &\quad \left. - \alpha_\beta \Gamma_{\alpha\gamma}^\beta dx^\gamma \right) \\ &= X^\alpha (\alpha_{\beta,\alpha} - \alpha_\gamma \Gamma_{\alpha\beta}^\gamma) dx^\beta \end{aligned}$$

Again we write

$$\nabla \frac{\partial}{\partial x^\alpha} (\alpha) = : (\nabla_\alpha \alpha_\delta) dx^\delta \quad (7.37)$$

$$\text{then } \nabla_\alpha \alpha = X^\alpha (\nabla_\alpha \alpha_\delta) dx^\delta \quad (7.38)$$

with

$$\nabla_\alpha \alpha_\beta = \alpha_{\beta,\alpha} - \Gamma_{\alpha\beta}^\gamma \alpha_\gamma \quad (7.39)$$

c) Let now generally  $T \in ST_m^r(H)$

$$T = T_{\beta_1 \dots \beta_m}^{d_1 \dots d_r} \frac{\partial}{\partial x^{\alpha_1}} \otimes \dots \otimes \partial x^{\beta_m} \quad (7.40)$$

Then

$$\nabla_x T = X^\delta \left( \nabla_\delta T_{\beta_1 \dots \beta_m}^{d_1 \dots d_r} \right) \frac{\partial}{\partial x^{\alpha_1}} \otimes \dots \otimes \partial x^{\beta_m} \quad (7.41)$$

with

$$\begin{aligned} \nabla_\delta T_{\beta_1 \dots \beta_m}^{d_1 \dots d_r} &= \frac{\partial}{\partial x^\delta} T_{\beta_1 \dots \beta_m}^{d_1 \dots d_r} \\ &+ \sum_{i=1}^r \prod_{\gamma}^{\delta_i} T_{\beta_1 \dots \beta_m}^{d_1 \dots d_{i-1} \lambda d_{i+1} \dots d_r} \\ &- \sum_{i=1}^m \prod_{\gamma}^{\lambda} T_{\beta_1 \dots \beta_{i-1} \lambda \beta_{i+1} \dots \beta_m}^{d_1 \dots d_r} \end{aligned} \quad (7.42)$$

The coefficients  $\nabla_\delta T_{\beta_1 \dots \beta_m}^{d_1 \dots d_r}$  are that of  $\nabla T \in ST_{m+1}^r(H)$ , i.e. a tensor.

The formulae for the coordinate expressions for  $\nabla_x T$  should be compared with those for the Lie-derivative  $L_x T$

Note the similarities in the systematics and differences in signs!

$$\begin{aligned}
 & (\nabla_x T) \Big|_{\beta_1 \dots \beta_m}^{d_1 \dots d_r} \\
 &= X^\alpha \frac{\partial}{\partial x} \Big|_{\beta_1 \dots \beta_m}^{d_1 \dots d_r} \\
 &+ \sum_{i=1}^r X^{\alpha} \frac{\partial}{\partial x^i} \Big|_{\beta_1 \dots \beta_m}^{d_1 \dots d_{i-1} \times d_{i+1} \dots d_r} \\
 &- \sum_{i=1}^m X^{\alpha} \frac{\partial}{\partial \beta_i} \Big|_{\beta_1 \dots \beta_{i-1} \times \beta_{i+1} \dots \beta_m}^{d_1 \dots d_r}
 \end{aligned}$$

(7.43)

$$\begin{aligned}
 & (T_x T) \Big|_{\beta_1 \dots \beta_m}^{d_1 \dots d_r} \\
 &= X^\alpha \frac{\partial}{\partial x} \Big|_{\beta_1 \dots \beta_m}^{d_1 \dots d_r} \\
 &- \sum_{i=1}^r X^{\alpha} \frac{\partial}{\partial x^i} \Big|_{\beta_1 \dots \beta_m}^{d_1 \dots d_{i-1} \times d_{i+1} \dots d_r} \\
 &+ \sum_{i=1}^m X^{\alpha} \frac{\partial}{\partial \beta_i} \Big|_{\beta_1 \dots \beta_{i-1} \times \beta_{i+1} \dots \beta_m}^{d_1 \dots d_r}
 \end{aligned}$$

(7.44)

$$\begin{aligned}
 &= X^\alpha \nabla_x T \Big|_{\beta_1 \dots \beta_m}^{d_1 \dots d_r} \\
 &- \sum_{i=1}^r (\nabla_x X^{\alpha i}) \Big|_{\beta_1 \dots \beta_m}^{d_1 \dots d_{i-1} \times d_{i+1} \dots d_r} \\
 &+ \sum_{i=1}^m (\nabla_{\beta_i} X^\alpha) \Big|_{\beta_1 \dots \beta_{i-1} \times \beta_{i+1} \dots \beta_m}^{d_1 \dots d_r}
 \end{aligned}$$

(7.45)

## Examples

$$\begin{aligned}
 1) \quad \nabla_\gamma g_{\alpha\beta} &= g_{\alpha\beta,\gamma} - g_{\lambda\beta} \Gamma_{\gamma\alpha}^\lambda - g_{\alpha\lambda} \Gamma_{\gamma\beta}^\lambda \\
 &= 0
 \end{aligned} \tag{7.46}$$

$$\begin{aligned}
 2) \quad \nabla_\gamma g^{\alpha\beta} &= g^{\alpha\beta}{}_{,\gamma} + \Gamma_{\gamma\lambda}^\alpha g^{\lambda\beta} + \Gamma_{\gamma\lambda}^\beta g^{\alpha\lambda} \\
 &= 0
 \end{aligned} \tag{7.47}$$

$$\begin{aligned}
 3) \quad \nabla_\gamma \delta^\alpha_\beta &= \delta^\alpha_{\beta,\gamma} + \Gamma_{\gamma\lambda}^\alpha \delta^\lambda_\beta - \Gamma_{\gamma\beta}^\lambda \delta^\alpha_\lambda \\
 &= 0
 \end{aligned} \tag{7.48}$$

$$\begin{aligned}
 4) \quad (L \times g)_{\alpha\beta} &= X^\gamma g_{\alpha\beta,\gamma} - X^\lambda{}_{,\alpha} g_{\lambda\beta} - X^\lambda{}_{,\beta} g_{\alpha\lambda} \\
 &= X^\gamma \nabla_\gamma g_{\alpha\beta} + \nabla_\alpha X^\lambda g_{\lambda\beta} + \nabla_\beta X^\lambda g_{\alpha\lambda} \\
 &= 0 + \nabla_\alpha (X^\lambda g_{\lambda\beta}) + \nabla_\beta (X^\lambda g_{\alpha\lambda}) \\
 &= \nabla_\alpha X_\beta + \nabla_\beta X_\alpha \\
 &= 2 \nabla_{(\alpha} X_{\beta)}
 \end{aligned} \tag{7.49}$$

5) Let  $T$  be a symmetric, divergence free tensor:  $T^{\alpha\beta} = T^{\beta\alpha}$ ,  $\nabla_\alpha T^{\alpha\beta} = 0$ , then

$$\begin{aligned}
 \nabla_\alpha (T^{\alpha\beta} X_\beta) &= T^{\alpha\beta} \nabla_\alpha X_\beta \\
 &= T^{\alpha\beta} \nabla_{(\alpha} X_{\beta)} \\
 &= (1/2) T^{\alpha\beta} (L \times g)_{\alpha\beta}
 \end{aligned} \tag{7.50}$$

Hence: if  $X$  satisfies  $L \times g = 0 \Rightarrow T^{\alpha\beta} X_\beta$  is divergence-free.