

Sheet 11: SolutionsProblem 1

$$R_{0101} = -R_{2323} = \frac{\tau_5}{\tau_3}$$

$$R_{0202} = R_{0303}$$

$$= -R_{1212}$$

$$= -R_{1313} = -\frac{1}{2} \frac{\tau_5}{\tau_3}$$

(11.1.1)

Lorentz-Transformation in radial direction

$$\{\Lambda^{\alpha}_{\beta}\} = \begin{pmatrix} \cosh(\alpha) & \sinh(\alpha) & 0 & 0 \\ \sinh(\alpha) & \cosh(\alpha) & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad (11.1.2)$$

$$\Theta^{\alpha} \mapsto \hat{\Theta}^{\alpha} := \Lambda^{\alpha}_{\beta} \Theta^{\beta} \quad (11.1.3)$$

$$R = R_{\alpha\beta\mu\nu} \Theta^{\alpha} \otimes \Theta^{\beta} \otimes \Theta^{\mu} \otimes \Theta^{\nu}$$

$$\rightarrow \hat{R} := \Lambda^{\otimes 4}(R) = R_{\alpha\beta\mu\nu} \hat{\Theta}^{\alpha} \otimes \dots \otimes \hat{\Theta}^{\nu}$$

$$= \hat{R}_{\alpha\beta\mu\nu} \Theta^{\alpha} \otimes \dots \otimes \Theta^{\nu}$$

$$\text{where } \hat{R}_{\alpha\beta\mu\nu} = R_{\lambda\sigma\kappa\epsilon} \Lambda^{\lambda}_{\alpha} \Lambda^{\sigma}_{\beta} \Lambda^{\kappa}_{\mu} \Lambda^{\epsilon}_{\nu}$$

(11.1.4)

Have

$$\left. \begin{aligned} \Lambda^M_0 &= \cosh(\alpha) \delta^M_0 + \sinh(\alpha) \delta^M_1 \\ \Lambda^M_1 &= \sinh(\alpha) \delta^M_0 + \cosh(\alpha) \delta^M_1 \\ \Lambda^M_2 &= \delta^M_2 \\ \Lambda^M_3 &= \delta^M_3 \end{aligned} \right\} (11.1.5)$$

This gives

$$\begin{aligned} \hat{R}_{0101} &= R_{\alpha\beta\mu\nu} \Lambda^\alpha_0 \Lambda^\beta_1 \Lambda^\mu_0 \Lambda^\nu_1 \\ &= R_{0101} (\cosh^2(\alpha) - \sinh^2(\alpha))^2 \\ &= R_{0101} \end{aligned} \quad (11.1.7)$$

$$\begin{aligned} \hat{R}_{2323} &= R_{\alpha\beta\mu\nu} \Lambda^\alpha_2 \Lambda^\beta_3 \Lambda^\mu_2 \Lambda^\nu_3 \\ &= R_{2323} \end{aligned} \quad (11.1.8)$$

$$\begin{aligned} \hat{R}_{1212} &= R_{\alpha\beta\mu\nu} \Lambda^\alpha_1 \Lambda^\beta_2 \Lambda^\mu_1 \Lambda^\nu_2 \\ &= R_{\alpha 2 \mu 2} \Lambda^\alpha_1 \Lambda^\mu_1 \\ &= \sinh^2(\alpha) \underbrace{R_{0202}}_{=-R_{1212}} + \cosh^2(\alpha) R_{1212} \\ &\quad + 2 \underbrace{R_{0212}}_{=0} \sinh(\alpha) \cosh(\alpha) \\ &= R_{1212} \end{aligned} \quad (11.1.9)$$

$$\begin{aligned}\hat{R}_{1313} &= \text{Same as for } R_{1212} \\ &= R_{1313} \quad (11.1.10)\end{aligned}$$

$$\begin{aligned}\hat{R}_{0202} &= R_{\alpha\beta\mu\nu} \Lambda_0^\alpha \Lambda_2^\beta \Lambda_0^\mu \Lambda_2^\nu \\ &= R_{\alpha 2 \mu 2} \Lambda_0^\alpha \Lambda_0^\mu \\ &= R_{0202} \cosh^2(\alpha) \\ &\quad + \underbrace{R_{1212}}_{= R_{0202}} \sinh^2(\alpha) \\ &\quad + 2 \sinh(\alpha) \cosh(\alpha) \underbrace{R_{0212}}_{= 0} \\ &= R_{0202} \quad (11.1.11)\end{aligned}$$

$$\begin{aligned}\hat{R}_{0303} &= \text{Same as for } R_{0202} \\ &= R_{0303} \quad (11.1.12)\end{aligned}$$

Showing so far that for the index combinations (0101), (0202), (0303), (1212), (1313), and (2323) the components are as before.

But there will also be no new non-zero components, e.g.

$$\begin{aligned}
\hat{R}_{0212} &= R_{\alpha\beta\mu\nu} \Lambda^{\alpha}_0 \Lambda^{\beta}_2 \Lambda^{\mu}_1 \Lambda^{\nu}_2 \\
&= R_{\alpha 2 \mu 2} \Lambda^{\alpha}_0 \Lambda^{\mu}_1 \\
&= \underbrace{R_{1212}}_{=-R_{0202}} \sinh(\alpha) \cosh(\alpha) \\
&\quad + R_{0202} \sinh(\alpha) \cosh(\alpha) \\
&\quad + \cancel{R_{0212}^0} \cosh^2(\alpha) \\
&\quad + \cancel{R_{1202}^0} \cosh^2(\alpha) \\
&= 0
\end{aligned}$$

(11.1.13)

Problem 2

From

$$\frac{d^2 h^a}{d\tau^2} = c^2 R^a{}_{00b} h^b \quad (11.2.1)$$

and (11.1.1)

$$\begin{aligned} R_{0101} &= -2 R_{0202} = -2 R_{0303} \\ &= \tau_s / \tau^3 \end{aligned}$$

hence

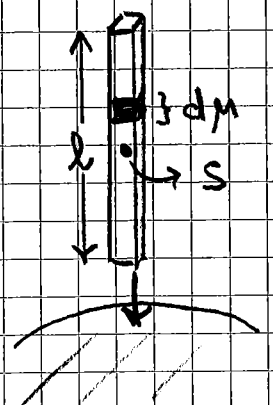
$$\begin{aligned} R^1{}_{001} &= -2 R^2{}_{002} = -2 R^3{}_{003} \\ &= \tau_s / \tau^3 \end{aligned} \quad (11.2.2)$$

we immediately get

$$\frac{d^2 h^1}{d\tau^2} = c^2 \frac{\tau_s}{\tau^3} h^1 \quad (11.2.3)$$

$$\frac{d^2 h^{2,3}}{d\tau^2} = -\frac{c^2}{2} \frac{\tau_s}{\tau^3} h^{2,3} \quad (11.2.4)$$

Consider an elastic rod falling, end first, radially in the grav.-field. A mass-element  $d\mu$  at height  $h$  above the centre point suffers outward force of



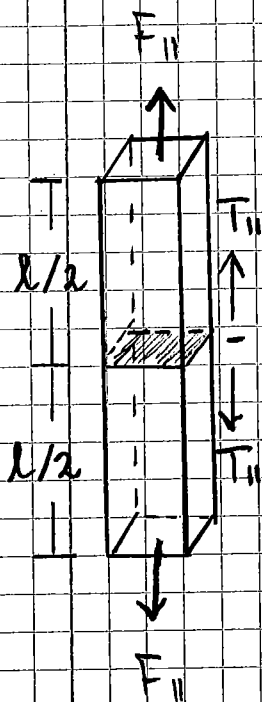
according to (11.2.3)

$$dF_{\parallel} = \left( c^2 \tau_s \frac{h}{\tau^3} \right) d\mu \quad (11.2.5)$$

that tries to separate it from the centre  $S$ . For a homogeneous rod with cross section  $q = b^2$  of square shape (side length =  $b$ ) we get as total outward pulling force (for  $h \ll \tau$ )

$$F_{\parallel} = c^2 \frac{\tau_s}{\tau^3} \int_0^{l/2} q g h \, dh$$

$$= c^2 \frac{\tau_s}{\tau^3} q g \frac{l^2}{8} \quad (11.2.6)$$



The tension on the cross-section at the mid-part is

$$\begin{aligned} T_{\parallel} &= \frac{F_{\parallel}}{q} \\ &= \frac{1}{8} \cdot g c^2 \left( \frac{l}{\tau_s} \right)^2 \left( \frac{\tau_s}{\tau} \right)^3 \end{aligned} \quad (11.2.7)$$

(longitudinal stress)

The transverse stress is  $-\frac{1}{2}$  that (pressure).

If we write  $r_s = 2GM/c^2$  in (11.2.7) we get

$$\begin{aligned}
 T_{11} &= \frac{1}{8} \rho c^2 r^2 \left( \frac{c^2}{2GM} \right)^2 \left( \frac{r_s}{r} \right)^3 \\
 &= \frac{1}{32} \rho r^2 \frac{c^6}{G^2 M^2} \left( \frac{r_s}{r} \right)^3 \\
 &= \rho r^2 \cdot \underbrace{\frac{1}{32} \cdot \frac{c^6}{G^2 (10^4 M_\odot)^2}}_{12.7 \text{ s}^{-2}} \cdot \left( \frac{10^4 M_\odot}{M} \right)^2 \left( \frac{r_s}{r} \right)^3
 \end{aligned}
 \tag{11.2.8}$$

Hence

$$\begin{aligned}
 T_{11} [\text{N} \cdot \text{m}^{-2}] &= 12.7 \times \rho [\text{kg} \cdot \text{m}^{-3}] \times r^2 [\text{m}] \\
 &\quad \times (10^4 M_\odot / M)^2 \times (r_s / r)^3 \\
 &= 1.27 \times 10^4 \times \rho [\text{g} \cdot \text{cm}^{-3}] \times r^2 [\text{m}] \\
 &\quad \times (10^4 M_\odot / M)^2 \times (r_s / r)^3
 \end{aligned}
 \tag{11.2.9}$$

Problem 3Part 1 Neutron star

$$M = 1.5 M_{\odot}$$

$$r_s = 4.5 \text{ km}$$

$$r = R = 10 \text{ km}$$

$$\left. \begin{array}{l} M = 1.5 M_{\odot} \\ r_s = 4.5 \text{ km} \\ r = R = 10 \text{ km} \end{array} \right\} (11.3.1)$$

$$\Rightarrow (r_s/r) = 0.45$$

$$\begin{aligned} \text{Red } \rho &= 7.85 \text{ g} \cdot \text{cm}^{-3} \\ &= 7.85 \cdot 10^3 \text{ kg} \cdot \text{m}^{-3} \end{aligned}$$

$$\lambda = 25 \text{ m}$$

$$\begin{aligned} \sigma_{\text{max}} &= 2.1 \cdot 10^3 \text{ N/mm}^2 \\ &= 2.1 \cdot 10^9 \text{ N} \cdot \text{m}^{-2} \end{aligned}$$

$$\left. \begin{array}{l} \rho = 7.85 \text{ g} \cdot \text{cm}^{-3} \\ \lambda = 25 \text{ m} \\ \sigma_{\text{max}} = 2.1 \cdot 10^3 \text{ N/mm}^2 \end{array} \right\} (11.3.2)$$

$$\begin{aligned} T_{\parallel} [\text{N} \cdot \text{m}^2] &= 12.7 \times 7.85 \cdot 10^3 \cdot (25)^2 \cdot \left( \frac{10^4}{1.5} \right)^2 (0.45)^3 \\ &= 2.5 \cdot 10^{14} \gg \sigma_{\text{max}} \end{aligned} \quad (11.3.3)$$

Since this is quadratic in  $\lambda$ , the length  $\lambda_{\text{max}}$  at which this would equal would be the  $n$ 'th part of  $\lambda = 25 \text{ m}$ , where

$$n = (T_{\parallel} / \sigma_{\text{max}})^{1/2} = 346.7 \quad (11.3.4)$$



A piece not piece larger than

$$\frac{25 \text{ m}}{346.7} = \lambda_{\text{max}} = 7.2 \text{ cm} \quad (11.3.5)$$

reaches the surface of the neutron star.  
The rod breaks into at least 347 pieces.

Part 2

Human body

$$\lambda = 1.8 \text{ m}$$

$$\rho = 1 \text{ g} \cdot \text{cm}^{-3}$$

} (11.3.6)

From (11.2.9)

$$\begin{aligned} \bar{T} \text{ [N} \cdot \text{m}^{-2}] &= 1.27 \times 10^4 \cdot (1.8)^2 \left( \frac{10^4 M_{\odot}}{M} \right)^2 \left( \frac{1 \text{ s}}{\pi} \right)^3 \\ &= 4.1 \times 10^4 \left( \frac{10^4 M_{\odot}}{M} \right)^2 \left( \frac{1 \text{ s}}{\pi} \right)^3 \end{aligned} \quad (11.3.7)$$

If a mass of 100 kg hangs on your feet while your hands held on to a high bar, a force of  $10^3 \text{ N}$  will be distributed over your cross-sectional area of  $(0.33 \text{ m})^2 = 0.1 \text{ m}^2$  giving rise to a tension at the "pain limit" of  $10^4 \text{ N m}^{-2}$

$$E = 10^4 \text{ N m}^{-2} = 10^4 \text{ Kg m}^{-1} \text{ s}^{-2} = 10^5 \text{ g} \cdot \text{cm}^{-1} \text{ s}^{-2} \quad (11.3.8)$$

Hence

$$\frac{T_{II}}{E} = 4.1 \cdot \left( \frac{10^4 M_{\odot}}{M} \right)^2 \left( \frac{\tau_s}{\tau} \right)^3 \quad (11.3.9)$$

Or for  $\tau = \tau_s$ , i.e. jumping through the horizon,

$$\frac{T_{II}}{E} = 4.1 \left( \frac{M}{10^4 M_{\odot}} \right)^{-2} \quad (11.3.10)$$

→ relatively "painless" for  $M \gg 10^4 M_{\odot}$

For the galactic Black Hole have

$$M = 4.1 \times 10^6 M_{\odot} \quad (11.3.11)$$

$$\leadsto \frac{T_{II}}{E} = 2.4 \cdot 10^{-5} \quad (11.3.12)$$

Like a mass of  $\approx 10^{-2}$  grams hanging on your feet; i.e. you will feel nothing!

Problem 4

$$\begin{aligned}
 g &= \left(1 - \frac{r_s}{r}\right) c dt \otimes c dt \\
 &- \left(1 - \frac{r_s}{r}\right)^{-1} dr \otimes dr \\
 &- r^2 (d\theta \otimes d\theta + \sin^2(\theta) d\varphi \otimes d\varphi)
 \end{aligned}
 \quad \left. \vphantom{\begin{aligned} g \\ \\ \\ \end{aligned}} \right\} \text{(11.4.1)}$$

Any timelike curve  $(t(\tau), r(\tau), \theta(\tau), \varphi(\tau))$  satisfies

$$\begin{aligned}
 \left(1 - \frac{r_s}{r}\right) c^2 \dot{t}^2 - \left(1 - \frac{r_s}{r}\right)^{-1} \dot{r}^2 \\
 - r^2 (\dot{\theta}^2 + \sin^2(\theta) \dot{\varphi}^2) = c^2
 \end{aligned}$$

or

$$\begin{aligned}
 \dot{r}^2 &= \left(\frac{r_s}{r} - 1\right) \left[ c^2 + r^2 (\dot{\theta}^2 + \sin^2(\theta) \dot{\varphi}^2) \right] \\
 &+ \left(\frac{r_s}{r} - 1\right)^2 c^2 \dot{t}^2 \\
 &> \left(\frac{r_s}{r} - 1\right) c^2
 \end{aligned}
 \quad \text{(11.4.2)}$$

for  $r < r_s$

If the curve has entered the region  $r < r_s$  so that  $\dot{r} < 0$  for  $r$  just below, then

$$-\dot{\tau} > \left(\frac{\tau_s}{\tau} - 1\right)^2 c$$

$$\rightarrow -\frac{d\tau}{\left(\frac{\tau_s}{\tau} - 1\right)^{1/2}} > c d\tau \quad (11.4.3)$$

for all future  $\tau$ . Hence the time until  $\uparrow(t)$  reaches  $\tau = 0$  is bounded above

$$\int d\tau = \tau < -\frac{1}{c} \int_{\tau=\tau_s}^{\tau=0} \frac{d\tau'}{\left(\frac{\tau_s}{\tau'} - 1\right)^{1/2}}$$

$$\text{But } \int_{\tau_s}^0 \frac{d\tau'}{\left(\frac{\tau_s}{\tau'} - 1\right)^{1/2}} = -\tau_s \int_0^1 \frac{dx}{\left(\frac{1}{x} - 1\right)^{1/2}}$$

$$= -\tau_s \int_0^1 \frac{x dx}{(x - x^2)^{1/2}} \quad x = \frac{\tau'}{\tau_s}$$

$$= -\tau_s \int_0^1 \frac{x dx}{\left[\frac{1}{4} - \left(x - \frac{1}{2}\right)^2\right]^{1/2}}$$

$$= -2\tau_s \int_0^1 \frac{x dx}{\left[1 - (2x-1)^2\right]^{1/2}} \quad 2x-1 = y$$

$$= -\frac{\tau_s}{2} \int_{-1}^{+1} \frac{(y+1) dy}{(1-y^2)^{1/2}} = -\frac{\tau_s}{2} \int_{-1}^{+1} \frac{dy}{(1-y^2)^{1/2}}$$

$$= -\frac{\tau_s}{2} \sin^{-1}(y) \Big|_{-1}^{+1} = -\frac{\pi}{2} \tau_s \quad (11.4.4)$$

Hence

$$\tau < \frac{\pi}{2} \left( \frac{r_s}{c} \right) \quad (11.4.5)$$

The upper bound  $\frac{\pi}{2} (r_s/c)$  is what we found for the radial geodesic in Lecture 19, Equation (19.54) for  $R = r_s$ .

For the galactic black hole with

$$\begin{aligned} M &= 4.1 \times 10^6 M_\odot \\ \approx r_s &= 1.2 \times 10^{10} \text{ m} \end{aligned} \quad \left. \vphantom{\begin{aligned} M \\ \approx r_s \end{aligned}} \right\} (11.4.6)$$

have

$$\tau < 63.8 \text{ s} \quad (11.4.7)$$

So your remaining lifetime is about a minute before you get "spaghettified".

Boosting your spaceship and all other measures only shorten your lifetime. Timelike geodesics are the longest among all timelike curves connecting the same points.

Problem 5

$$\begin{aligned}
 g &= \left(1 - \frac{r_s}{r}\right) c dt \otimes c dt \\
 &\quad - \left(1 - \frac{r_s}{r}\right)^{-1} dr \otimes dr \\
 &\quad - r^2 d\Omega^2
 \end{aligned}$$

$$= \left(1 - \frac{r_s}{r}\right) \left\{ c dt \otimes c dt - \underbrace{\frac{dr \otimes dr}{\left(1 - \frac{r_s}{r}\right)^2}} \right\} - r^2 d\Omega^2.$$

(11.5.1)

define  $r_*$  so  
that this equals  
 $dr_* \otimes dr_*$

$$\Rightarrow dr_* = \frac{dr}{1 - \frac{r_s}{r}}$$

$$= \frac{r dr}{r - r_s}$$

$$= r_s \frac{x dx}{x-1}$$

(11.5.2)

where  $x := r/r_s$

$$\frac{x dx}{x-1} = \left(1 + \frac{1}{x-1}\right) dx$$

$$= d\left(x + \ln|x-1|\right)$$

Hence

$$\begin{aligned} r^* &= r_s \left( \frac{1}{r_s} + \ln \left| \frac{r}{r_s} - 1 \right| \right) \\ &= r + r_s \ln \left| \frac{r}{r_s} - 1 \right| \quad (11.5.3) \end{aligned}$$

$$\begin{aligned} g &= \left( 1 - \frac{r_s}{r} \right) (c dt \otimes c dt - dt^* \otimes dr^*) \\ &\quad - r^2 d^2 \Omega \quad (11.5.4) \end{aligned}$$

For

$$\left. \begin{aligned} u &:= ct - r^*(r) \\ v &:= ct + r^*(r) \end{aligned} \right\} (11.5.5)$$

have

$$\begin{aligned} du \otimes dv &= (dct - dr^*) \otimes (dct + dr^*) \\ &= dct \otimes dct - dr^* \otimes dr^* \\ &\quad + dct \wedge dr^* \quad (11.5.6) \end{aligned}$$

Hence, if we write

$$du \vee dv := \frac{1}{2} (du \otimes dv + dv \otimes du) \quad (11.5.7)$$

for the symmetrized tensor product, then

$$du \, v \, dv = dc \, t \otimes dc \, t - dr_* \otimes dr_* \quad (11.5.8)$$

and

$$g = \left(1 - \frac{r_s}{r}\right) du \, v \, dv - r^2 d\Omega. \quad (11.5.9)$$

where  $r = r(u, v)$ .

Note that for the Jacobian for the transformation

$$(ct, r) \rightarrow (u(ct, r), v(ct, r))$$

$$\begin{pmatrix} u_{,ct} & u_{,r} \\ v_{,ct} & v_{,r} \end{pmatrix} = \begin{pmatrix} 1 & -\frac{r'}{c} \\ 1 & +\frac{r'}{c} \end{pmatrix} \quad (11.5.10)$$

the determinant of which is

$$2 r_*' = 2 \left(1 - \frac{r_s}{r}\right)^{-1} \quad (11.5.11)$$

Radial lightlike geodesics obey

$$\left(1 - \frac{r_s}{r}\right) \dot{c}t^2 = \tilde{E} = \text{const} \quad (11.5.12)$$

$$\left(1 - \frac{r_s}{r}\right) c^2 \dot{t}^2 - \left(1 - \frac{r_s}{r}\right)^{-1} \dot{r}^2 = 0 \quad (11.5.13)$$



We eliminate  $\dot{t}$  in the second equation through the first, i.e.

$$\dot{t} = (\tilde{E}/c) \left(1 - \frac{v_s}{c}\right)^{-1} \quad (11.5.14)$$

then

$$\left(1 - \frac{v_s}{c}\right) c^2 \left(\frac{\tilde{E}}{c^2}\right)^2 \left(1 - \frac{v_s}{c}\right)^{-2} - \left(1 - \frac{v_s}{c}\right)^{-1} \dot{t}^2 = 0$$

$$\Rightarrow \dot{t} = \pm \tilde{E}/c \quad (11.5.15)$$

So  $\tau$  as function of an affine parameter is simply

$$\tau(\lambda) = \pm (\tilde{E}/c) \lambda + \tau_0 \quad (11.5.16)$$

where  $\tau(\lambda=0) = \tau_0$ . In order to get  $\tau$  as function of  $t$  we look at the quotient

$$\frac{\dot{\tau}}{\dot{t}} = \frac{d\tau}{dt} = \pm c \left(1 - \frac{v_s}{c}\right) \quad (11.5.16)$$

which is equivalent to

$$\left(1 - \frac{v_s}{c}\right)^{-1} \frac{d\tau}{dt} = \pm c \quad (11.5.17)$$

The left hand side is clearly just  $d\tau^*/dt$ , i.e. (11.5.17) is equivalent

to

$$\frac{d\tau^*}{dt} = \pm c \quad (11.5.18)$$

$$\Rightarrow \tau^*(t) = \pm ct + \tau_0^* \quad (11.5.19)$$

where  $\tau_0^* = \tau^*(t=0)$

For an outgoing null ray we take the upper sign and (11.5.19) is equivalent to

$$u = ct - \tau^*(t) = -\tau_0^* = k \quad (11.5.20)$$

Hence the curve  $u = k = \text{const.}$  is a radial lightlike autoparallel that intersects the hypersurface  $t = 0$  at  $\tau^*(t=0) = -k$ , i.e. at

$$\tau(t=0) = \tau_*^{-1}(-k) \quad (11.5.20)$$

Likewise the curve  $v = k = \text{const.}$  corresponds to

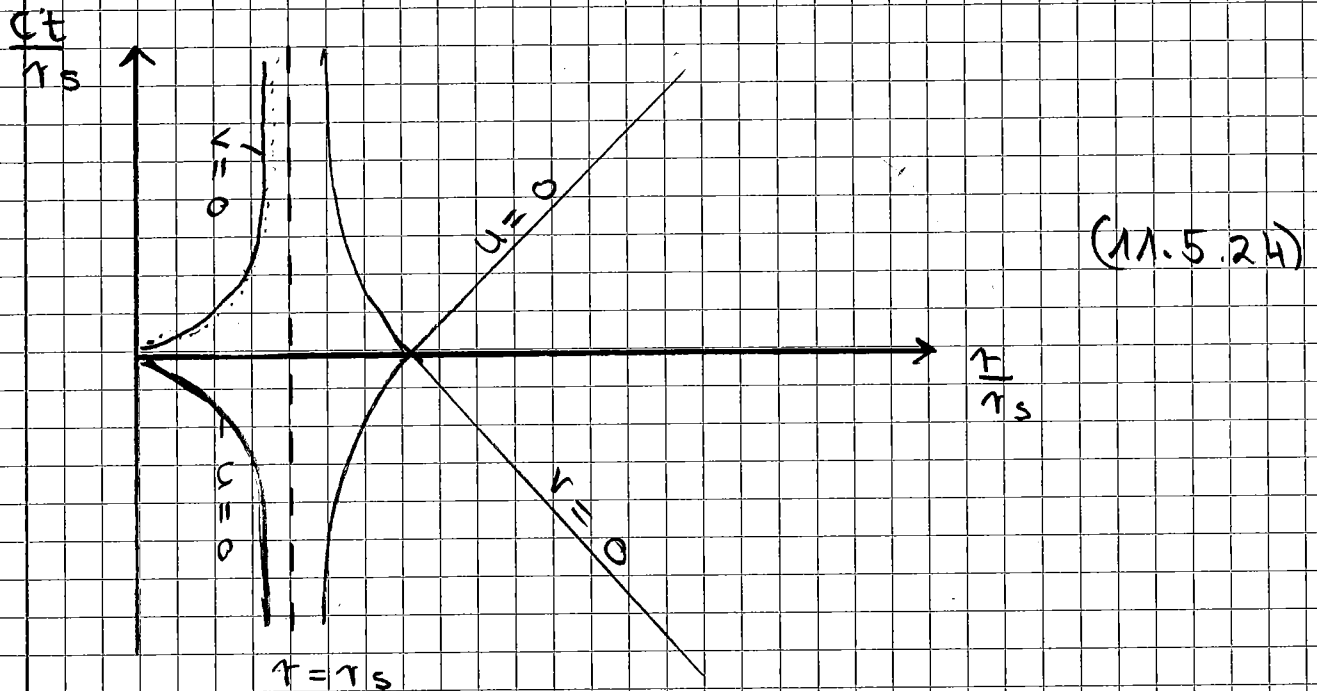
$$v = ct + \tau^*(t) = \tau_0^* = k \quad (11.5.21)$$

i.e. an ingoing null ray intersecting  $t = 0$  at

$$\tau(t=0) = \tau_*^{-1}(k). \quad (11.5.22)$$

The curves  $u = 0$  and  $v = 0$   
obey

$$\frac{ct}{r_s} = \pm \left( \frac{r}{r_s} + \ln \left| \frac{r}{r_s} - 1 \right| \right) \quad (11.5.23)$$



Finally we mention the possibility to replace  $t$  by either  $u$  or  $v$ , but to retain  $r$ , i.e. to make the coordinate transformations (EFC = Eddington-Finkelstein coordinates).

$$\left. \begin{aligned} (ct, r, \theta, \varphi) &\rightarrow (u, r, \theta, \varphi) \\ &\text{called "outgoing EFC"} \end{aligned} \right\} (11.5.25)$$

$$\left. \begin{aligned} (ct, r, \theta, \varphi) &\rightarrow (v, r, \theta, \varphi) \\ &\text{called "ingoing" EFC} \end{aligned} \right\} (11.5.26)$$

For the outgoing EFC the metric is

$$\begin{aligned}
 g &= \left(1 - \frac{r_s}{r}\right) (du + r' dr)^{\otimes 2} \\
 &\quad - \left(1 - \frac{r_s}{r}\right)^{-1} dr \otimes dr - r^2 d^2 \Omega \\
 &= \left(1 - \frac{r_s}{r}\right) du \otimes du \\
 &\quad + du \otimes dr + dr \otimes du \\
 &\quad - r^2 d^2 \Omega
 \end{aligned} \tag{11.5.27}$$

and for the ingoing EFC

$$\begin{aligned}
 g &= \left(1 - \frac{r_s}{r}\right) (dv - r' dr)^{\otimes 2} \\
 &\quad - \left(1 - \frac{r_s}{r}\right)^{-1} dr \otimes dr - r^2 d^2 \Omega \\
 &= \left(1 - \frac{r_s}{r}\right) dv \otimes dv \\
 &\quad - dv \otimes dr - dr \otimes dv \\
 &\quad - r^2 d^2 \Omega
 \end{aligned} \tag{11.5.28}$$

Clearly the metric coefficients are regular  $\forall r > 0$ . The value of  $\det \{g_{\alpha\beta}\}$  is

$$\det \{g_{\alpha\beta}\} = -r^4 \sin^2(\theta). \tag{11.5.29}$$

Note that the vector field  $\frac{\partial}{\partial r}$  in the outgoing EFC is not identical with  $\frac{\partial}{\partial r}$  in ingoing EFC

$$\left(\frac{\partial}{\partial r}\right)_{u, \theta, \varphi \text{ const}} \neq \left(\frac{\partial}{\partial r}\right)_{v, \theta, \varphi \text{ const}} \quad (11.5.30)$$

However, both are lightlike:

$$g\left(\frac{\partial}{\partial r}, \frac{\partial}{\partial r}\right) = 0 \quad (11.5.31)$$

For fixed  $(\theta, \varphi)$  it points along the lines of constant  $u$  in the first, and constant  $v$  in the second case.

Moreover

$$\begin{aligned} g\left(\frac{\partial}{\partial u}, \frac{\partial}{\partial u}\right) &= g\left(\frac{\partial}{\partial r}, \frac{\partial}{\partial r}\right) \\ &= \left(1 - \frac{rs}{r}\right) \end{aligned} \quad (11.5.32)$$

For outgoing EFC, any other lightlike vector in  $\text{Span}\{\partial_u, \partial_r\}$  is

$$X = a \frac{\partial}{\partial u} + b \frac{\partial}{\partial r} \quad (11.5.33)$$

$$\left. \begin{aligned} \text{with } g(X, X) &= 0 \iff \\ a^2 \left(1 - \frac{rs}{r}\right) + 2ab &= 0 \end{aligned} \right\} \quad (11.5.34)$$

Which except for  $a=0$ , i.e.  $X \sim \frac{\partial}{\partial r}$ ,  
has the further solution for  $a \neq 0$ :

$$b = -\frac{a}{2} \left(1 - \frac{rs}{r}\right). \quad (11.5.35)$$

So the lightlike directions are

$$\left. \begin{array}{l} \text{Span} \left\{ \frac{\partial}{\partial r} \right\} \\ \text{Span} \left\{ \frac{\partial}{\partial u} - \frac{1}{2} \left(1 - \frac{rs}{r}\right) \frac{\partial}{\partial r} \right\} \end{array} \right\} (11.5.36)$$

For ingoing EFC we set

$$X = a \frac{\partial}{\partial v} + b \frac{\partial}{\partial r} \quad (11.5.37)$$

and have

$$\left. \begin{array}{l} g(X, X) = 0 \Leftrightarrow \\ a^2 \left(1 - \frac{rs}{r}\right) - 2ab = 0 \end{array} \right\} (11.5.38)$$

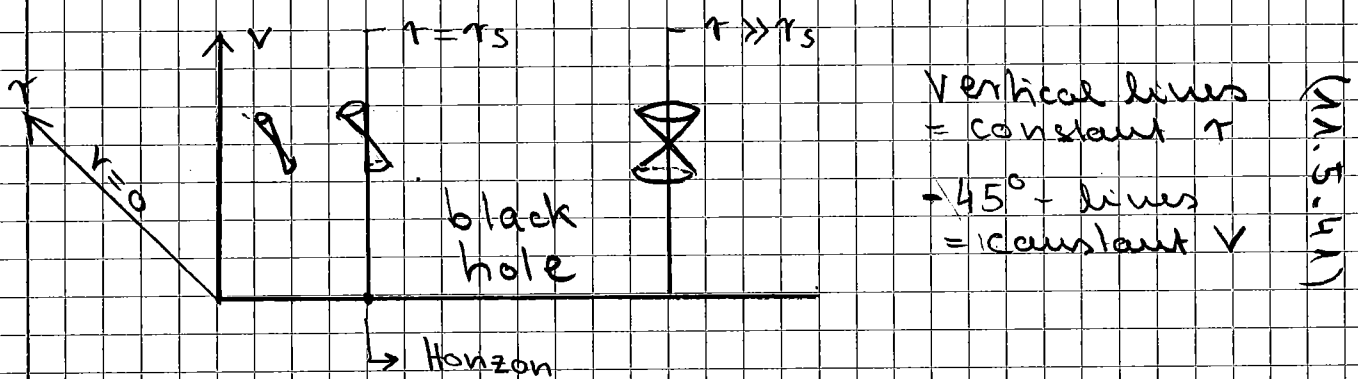
Which again except for  $a=0$ , i.e.  $X \sim \frac{\partial}{\partial r}$   
has the further solution for  $a \neq 0$ :

$$b = \frac{1}{2} \left(1 - \frac{rs}{r}\right) \quad (11.5.39)$$

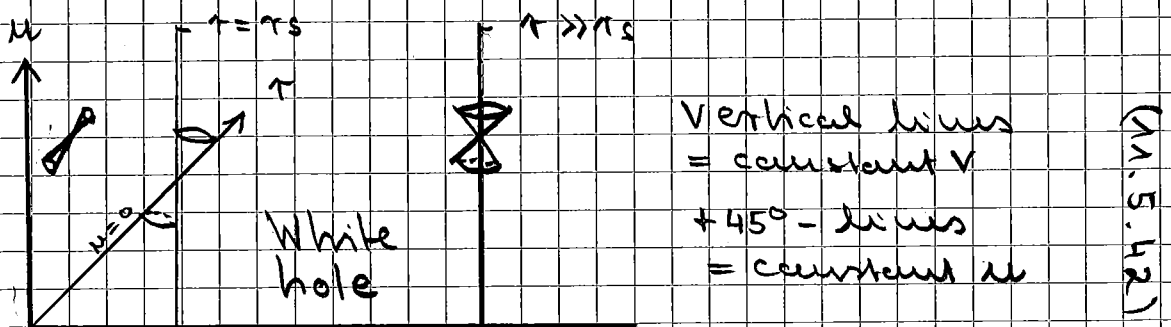
Hence for ingoing EFC the lightlike directions are

$$\left. \begin{aligned} \text{Span} \left\{ \frac{\partial}{\partial \tau} \right\} \\ \text{Span} \left\{ \frac{\partial}{\partial v} + \frac{1}{2} \left( 1 - \frac{r_s}{r} \right) \frac{\partial}{\partial \tau} \right\} \end{aligned} \right\} (11.5.40)$$

Here are the drawings of the  $(u, \tau)$  and  $(v, \tau)$  plane, where we begin with the latter:



Light cone: one side always  $\setminus$  at  $-45^\circ$   
 other side from  $/$  to  $\setminus$  as  $\tau \rightarrow 0$



Light cone: one side always  $/$  at  $+45^\circ$   
 other side from  $\setminus$  to  $/$  as  $\tau \rightarrow 0$

Problem 6

Given a metric of the form

$$\begin{aligned}
 g &= \phi \, c \, dt \otimes c \, dt \\
 &\quad - \phi^{-1} \, dr \otimes dr \\
 &\quad - r^2 (d\theta \otimes d\theta + \sin^2(\theta) \, d\varphi \otimes d\varphi)
 \end{aligned}
 \tag{11.6.1}$$

We can introduce a new time coordinate

$$cT(r,t) := ct + f(r)
 \tag{11.6.2}$$

so that

$$c \, dt = c \, dT - f' \, dr
 \tag{11.6.3}$$

then (11.6.1) becomes

$$\begin{aligned}
 g &= \phi (c \, dT - f' \, dr) \otimes (c \, dT - f' \, dr) \\
 &\quad - \phi^{-1} \, dr \otimes dr - r^2 \, d^2\Omega \\
 &= \phi \, c \, dT \otimes c \, dT \\
 &\quad - \phi f' (c \, dT \otimes dr + dr \otimes c \, dT) \\
 &\quad - (\phi^{-1} - f'^2 \phi) \, dr \otimes dr \\
 &\quad - r^2 \, d^2\Omega
 \end{aligned}
 \tag{11.6.4}$$



For this to be the spatially flat metric on  $dT=0$  slices one ought to have

$$\phi^{-1} - \rho^{12} \phi = 1$$

$$\text{or } \rho^{12} = \phi^{-2} - \phi^{-1} \quad (11.6.5)$$

Now, in our case

$$\phi = 1 - \frac{\gamma_S}{\pi} \quad (11.6.6)$$

hence

$$\begin{aligned} \phi^{-2} - \phi^{-1} &= \frac{1}{\left(1 - \frac{\gamma_S}{\pi}\right)^2} - \frac{1}{1 - \frac{\gamma_S}{\pi}} \\ &= \frac{\pi_S / \pi}{\left(1 - \frac{\gamma_S}{\pi}\right)^2} = \frac{\pi / \pi_S}{\left(\frac{\pi}{\pi_S} - 1\right)^2} \quad (11.6.7) \end{aligned}$$

$$\Rightarrow \rho^1 = \frac{\sqrt{\pi / \pi_S}}{\frac{\pi}{\pi_S} - 1} \quad (11.6.8)$$

where we have chosen the positive root.

$$\Rightarrow \rho(\gamma) = \pi_S \cdot \left\{ 2 \left(\frac{\pi}{\pi_S}\right)^{1/2} + \ln \frac{\sqrt{\pi / \pi_S} - 1}{\sqrt{\pi / \pi_S} + 1} \right\}$$

Inserting (11.6.8) into (11.6.4) and

$$\begin{aligned} \phi \, r' &= \left(1 - \frac{r_s}{r}\right) \frac{\sqrt{r_s/r}}{1 - \frac{r_s}{r}} \\ &= \sqrt{r_s/r} \end{aligned} \quad (11.6.10)$$

gives

$$\begin{aligned} g &= \left(1 - \frac{r_s}{r}\right) c \, dT \otimes c \, dT \\ &\quad - \left(\frac{r_s}{r}\right)^{1/2} (c \, dT \otimes dr + dr \otimes c \, dT) \\ &\quad - (dr \otimes dr + r^2 (d\theta \otimes d\theta + \sin^2(\theta) d\varphi \otimes d\varphi)) \end{aligned} \quad (11.6.11)$$

The matrix of coefficients is

$$\begin{pmatrix} \left(1 - \frac{r_s}{r}\right) & -\left(\frac{r_s}{r}\right)^{1/2} & 0 & 0 \\ -\left(\frac{r_s}{r}\right)^{1/2} & -1 & 0 & 0 \\ 0 & 0 & -r^2 & 0 \\ 0 & 0 & 0 & -r^2 \sin^2(\theta) \end{pmatrix} \quad (11.6.12)$$

the determinant of which is

$$\det \{g_{\alpha\beta}\} = -r^4 \sin^2 \theta \quad (11.6.13)$$

Radial geodesics obey (Lecture 19)

$$\left(1 - \frac{r_s}{r}\right) c^2 \dot{t}^2 = \tilde{E}^2 \quad (11.6.14)$$

$$\left(1 - \frac{r_s}{r}\right) c^2 \dot{t}^2 - \left(1 - \frac{r_s}{r}\right)^{-1} \dot{r}^2 = c^2 \quad (11.6.15)$$

$$\dot{t} = \left(\tilde{E}/c^2\right) \left(1 - \frac{r_s}{r}\right)^{-1/2}$$

$$\left(1 - \frac{r_s}{r}\right) c^2 \left(\frac{\tilde{E}}{c^2}\right)^2 \left(1 - \frac{r_s}{r}\right)^{-2}$$

$$- \left(1 - \frac{r_s}{r}\right)^{-1} \dot{r}^2 = c^2$$

$$\Rightarrow \dot{r}^2 + c^2 \left(1 - \frac{r_s}{r}\right) = \frac{\tilde{E}^2}{c^2} \quad (11.6.16)$$

Choose  $\tilde{E}$  such that  $\dot{r} = 0$  for  $r = \infty$ ,  
i.e.

$$\tilde{E} = c^2$$

then

$$\dot{r}^2 = c^2 \frac{r_s}{r}, \quad \dot{r} = -c \left(\frac{r_s}{r}\right)^{1/2} \quad (11.6.17)$$

$$\dot{t} = \left(1 - \frac{r_s}{r}\right)^{-1/2} \quad (11.6.18)$$

where we have chosen the negative root for  $\dot{r}$  to get infalling geodesics.

Hence the four-velocity of the radially infalling geodesics is

$$\begin{aligned}
 u &= \dot{t} \frac{\partial}{\partial t} + \dot{r} \frac{\partial}{\partial r} \\
 &= \left(1 - \frac{r_s}{r}\right)^{-1} \frac{\partial}{\partial t} - c \left(\frac{r_s}{r}\right)^{1/2} \frac{\partial}{\partial r} \\
 &= u^\alpha \frac{\partial}{\partial x^\alpha}
 \end{aligned}
 \quad \left. \vphantom{\begin{aligned} u &= \dot{t} \frac{\partial}{\partial t} + \dot{r} \frac{\partial}{\partial r} \\ &= \left(1 - \frac{r_s}{r}\right)^{-1} \frac{\partial}{\partial t} - c \left(\frac{r_s}{r}\right)^{1/2} \frac{\partial}{\partial r} \\ &= u^\alpha \frac{\partial}{\partial x^\alpha} \end{aligned}} \right\} (11.6.19)$$

$$\begin{aligned}
 u^{ct} &= c \left(1 - r_s/r\right)^{-1} \\
 u^r &= -c \left(r_s/r\right)^{1/2}
 \end{aligned}
 \quad \left. \vphantom{\begin{aligned} u^{ct} &= c \left(1 - r_s/r\right)^{-1} \\ u^r &= -c \left(r_s/r\right)^{1/2} \end{aligned}} \right\} (11.6.20)$$

The corresponding 1-form components for

$$u^\downarrow = g(u, \cdot) = u_\alpha dx^\alpha$$

are

$$\begin{aligned}
 u_{ct} &= g_{ctct} u^{ct} = c \\
 u_r &= g_{rr} u^r = c \left(1 - \frac{r_s}{r}\right)^{-1} \left(\frac{r_s}{r}\right)^{1/2}
 \end{aligned}
 \quad \left. \vphantom{\begin{aligned} u_{ct} &= g_{ctct} u^{ct} = c \\ u_r &= g_{rr} u^r = c \left(1 - \frac{r_s}{r}\right)^{-1} \left(\frac{r_s}{r}\right)^{1/2} \end{aligned}} \right\} (11.6.21)$$

$$\begin{aligned}
 u^\downarrow &= c \left( c dt + \frac{\left(r_s/r\right)^{1/2}}{1 - r_s/r} dr \right) \\
 &= c^2 dT
 \end{aligned}
 \quad \left. \vphantom{\begin{aligned} u^\downarrow &= c \left( c dt + \frac{\left(r_s/r\right)^{1/2}}{1 - r_s/r} dr \right) \\ &= c^2 dT \end{aligned}} \right\} (11.6.22)$$

↑ Gullstrand-Painlevé time

If we compare (11.6.20) with the Newtonian case where

$$\frac{1}{2} m \dot{r}^2 - \frac{GMm}{r} = E = 0 \quad (\dot{r} = 0 \text{ for } r \rightarrow \infty)$$

$$\leadsto \dot{r} = - (2GM/r)^{1/2} = -c (\pi_s/r)^{1/2} \quad (11.6.23)$$

We see that  $r(\tau)$  in the relativistic case is the same function as  $r(t)$  in the Newtonian case.

We now express  $\mathcal{L} = \mathcal{L}^{ct} \frac{\partial}{\partial ct} + \mathcal{L}^r \frac{\partial}{\partial r}$  in terms of  $\partial/\partial \tilde{T}$  and  $\partial/\partial \tilde{r}$ . Quite generally, for a coordinate change of the form

$$(t, r) \mapsto (\tilde{t}(t, r), \tilde{r}(t, r)) \quad (11.6.24)$$

we have

$$\begin{aligned} \mathcal{L} &= \mathcal{L}^{ct} \frac{\partial}{\partial ct} + \mathcal{L}^r \frac{\partial}{\partial r} \\ &= \mathcal{L}^{ct} \left( \frac{\partial ct}{\partial c\tilde{t}} \frac{\partial}{\partial c\tilde{t}} + \frac{\partial \tilde{r}}{\partial ct} \frac{\partial}{\partial \tilde{r}} \right) \\ &\quad + \mathcal{L}^r \left( \frac{\partial ct}{\partial r} \frac{\partial}{\partial c\tilde{t}} + \frac{\partial \tilde{r}}{\partial r} \frac{\partial}{\partial \tilde{r}} \right) \end{aligned} \quad (11.6.25)$$

Here  $\tilde{t} = T$ ,  $\tilde{r} = r$

so that  $\frac{\partial \tilde{t}}{\partial t} = 1$ ,  $\frac{\partial ct}{\partial r} = 0$ ,  $\frac{\partial \tilde{r}}{\partial r} = 1$ ,  $\frac{\partial \tilde{r}}{\partial ct} = 0$  (11.6.26)

hence

$$\begin{aligned}
 \mu &= \mu^{ct} \frac{\partial}{\partial ct} \\
 &+ \mu^r \left( \dot{\gamma} \frac{\partial}{\partial ct} + \frac{\partial}{\partial \tilde{r}} \right) \\
 &= (\mu^{ct} + \dot{\gamma} \mu^r) \frac{\partial}{\partial ct} + \mu^r \frac{\partial}{\partial \tilde{r}} \quad (11.G.27)
 \end{aligned}$$

$$\begin{aligned}
 \Rightarrow \mu^{ct} &= \mu^{ct} + \dot{\gamma} \mu^r \\
 &= c \left( 1 - \frac{r_s}{r} \right)^{-1} + \frac{\sqrt{r_s/r}}{1 - r_s/r} \left( -c \left( \frac{r_s}{r} \right)^{1/2} \right) \\
 &= c \quad (11.G.28)
 \end{aligned}$$

$$\mu^{\tilde{r}} = -c \left( \frac{r_s}{r} \right)^{1/2} \quad (11.G.29)$$

Or calling  $\tilde{r}$  again  $r$ :

$$\begin{aligned}
 \mu &= \frac{\partial}{\partial T} - c \left( \frac{r_s}{r} \right)^{1/2} \frac{\partial}{\partial r} \\
 &= \dot{T} \frac{\partial}{\partial T} - \dot{r} \frac{\partial}{\partial r} \quad (11.G.30)
 \end{aligned}$$

This says that  $\dot{T} = 1$  along the geodesic, i.e. that  $T$  is just the eigen time.

Problem 7

$$\left. \begin{aligned} ct(x, \xi) &= \xi \sinh(x) \\ x(x, \xi) &= \xi \cosh(x) \end{aligned} \right\} (11.7.1)$$

$$\frac{\partial ct}{\partial x} = \xi \cosh(x) \quad (11.7.2a)$$

$$\frac{\partial ct}{\partial \xi} = \sinh(x) \quad (11.7.2b)$$

$$\frac{\partial x}{\partial x} = \xi \sinh(x) \quad (11.7.2c)$$

$$\frac{\partial x}{\partial \xi} = \cosh(x) \quad (11.7.2d)$$

$$\det \begin{pmatrix} \frac{\partial ct}{\partial x} & \frac{\partial ct}{\partial \xi} \\ \frac{\partial x}{\partial x} & \frac{\partial x}{\partial \xi} \end{pmatrix}$$

$$= \det \begin{pmatrix} \xi \cosh(x) & \sinh(x) \\ \xi \sinh(x) & \cosh(x) \end{pmatrix} = \xi \quad (11.7.3)$$

$$d(ct) = \xi \cosh(x) dx + \sinh(x) d\xi \quad (11.7.4a)$$

$$dx = \xi \sinh(x) dx + \cosh(x) d\xi \quad (11.7.4b)$$

$$\begin{aligned}
 \eta &= d(ct) \otimes d(ct) - dx \otimes dx \\
 &= (\xi \cosh(\lambda) d\lambda + \sinh(\lambda) d\xi)^{\otimes 2} \\
 &\quad - (\xi \sinh(\lambda) d\lambda + \cosh(\lambda) d\xi)^{\otimes 2} \\
 &= \xi^2 d\lambda \otimes d\lambda - d\xi \otimes d\xi \quad (11.7.5)
 \end{aligned}$$

$$K = x \frac{\partial}{\partial(ct)} + ct \frac{\partial}{\partial x} \quad (11.7.6)$$

Integral curve  $\lambda \mapsto (ct(\lambda), x(\lambda))$

satisfies

$$c\dot{t} = x, \quad \dot{x} = ct \quad (11.7.7)$$

$$\leadsto c\ddot{t} = ct, \quad \ddot{x} = x \quad (11.7.8)$$

$$\leadsto ct(\lambda) = A e^\lambda + B e^{-\lambda} \quad (11.7.9a)$$

$$x(\lambda) = A e^\lambda - B e^{-\lambda} \quad (11.7.9b)$$

Initial condition  $ct(\lambda=0) = 0 \rightarrow B = -A$

$$\leadsto \left. \begin{aligned} ct(\lambda) &= \xi \sinh(\lambda) \\ x(\lambda) &= \xi \cosh(\lambda) \end{aligned} \right\} (11.7.10)$$

where  $\xi = 2A$ .

Proper length along integral curve

$$ds = (c^2 \dot{t}^2 - \dot{x}^2)^{1/2} d\lambda = (x^2 - (ct)^2)^{1/2} d\lambda = \xi d\lambda \quad (11.7.11)$$



→ Eigenline

$$d\tau = \frac{1}{c} ds = \frac{1}{c} d\lambda \quad (11.7.12)$$

$$\text{or } \tau = (\xi/c) \lambda \quad (11.7.13)$$

if  $\tau = 0$  for  $\lambda = 0$ .

Along the curve have

$$\begin{aligned} \frac{dct}{d\tau} &= \frac{c}{\xi} \frac{d}{d\lambda} ct = \frac{c}{\xi} ct \\ &= \frac{c}{\xi} x(\xi) = c \cosh(\lambda) \quad (11.7.14) \end{aligned}$$

$$\frac{d^2 ct}{d\tau^2} = \frac{c}{\xi} \frac{d}{d\lambda} c \cosh(\lambda) = \frac{c^2}{\xi} \sinh(\lambda) \quad (11.7.15)$$

$$\begin{aligned} \frac{dx}{d\tau} &= \frac{c}{\xi} \frac{d}{d\lambda} x = \frac{c}{\xi} \dot{x} \\ &= \frac{c}{\xi} c t(\lambda) = c \sinh(\lambda) \quad (11.7.16) \end{aligned}$$

$$\frac{d^2 x}{d\tau^2} = \frac{c}{\xi} \frac{d}{d\lambda} c \sinh(\lambda) = \frac{c^2}{\xi} \cosh(\lambda) \quad (11.7.17)$$

$$\begin{aligned} \Rightarrow \frac{d^2}{d\tau^2} (ct(\tau), x(\tau)) \\ = \frac{c^2}{\xi} (\sinh(\lambda), \cosh(\lambda)) \quad (11.7.18) \end{aligned}$$

The Mink.-Norm of that is  $c^2/\xi$ . (11.7.19)

Note

$$\begin{aligned} \frac{\partial}{\partial x} &= c \dot{t} \frac{\partial}{\partial ct} + \dot{x} \frac{\partial}{\partial x} \\ &= X \frac{\partial}{\partial ct} + ct \frac{\partial}{\partial x} = K \end{aligned} \quad (11.7.20)$$

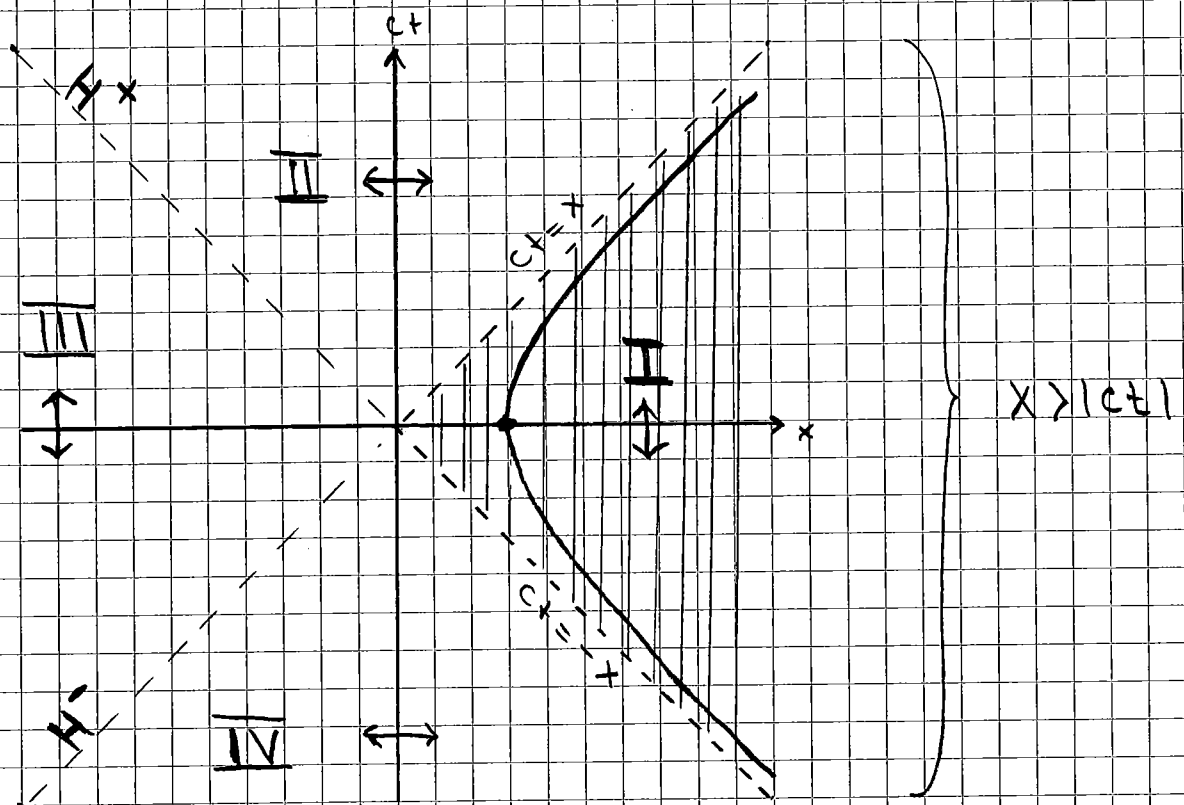
$\frac{\partial}{\partial x}$  = Vector field with integral lines

$$\xi \mapsto (ct(x, \xi), X(x, \xi)) \quad (11.7.21)$$

$\frac{\partial}{\partial x} \uparrow \frac{\partial}{\partial \xi}$  from

$$g = \epsilon^2 dx \otimes dx - d\xi \otimes d\xi$$

} (11.7.22)



The constantly accelerated observer on the hyperbola  $\xi = \text{const}$  is confined to region I:  $x > |ct|$ . He can receive signals from

$$I \cup IV = \{(ct, x) : ct - x < 0\} \quad (11.7.23)$$

and can send signals to

$$I \cup II = \{(ct, x) : ct + x > 0\} \quad (11.7.24)$$

He cannot receive any signals from

$$\overline{\text{II} \cup \text{III}} = \{ (ct, x) : ct - x \geq 0 \} \quad (11.7.25)$$

and he cannot send any signals to

$$\overline{\text{III} \cup \text{IV}} = \{ (ct, x) : ct + x \leq 0 \}$$

The causal complement is the region

$$\overline{\text{III}} = (\overline{\text{II} \cup \text{III}}) \cap (\overline{\text{III} \cup \text{IV}}) \quad (11.7.26)$$

of events from which the constantly accelerated observer can neither receive nor to which he can send signals.

The boundary

$$\begin{aligned} \partial(\overline{\text{III}}) &:= \overline{\text{II} \cup \text{III}} - (\overline{\text{II} \cup \text{III}})^{\circ} \\ &= \{ (ct, x) : ct = x \} \end{aligned} \quad (11.7.27)$$

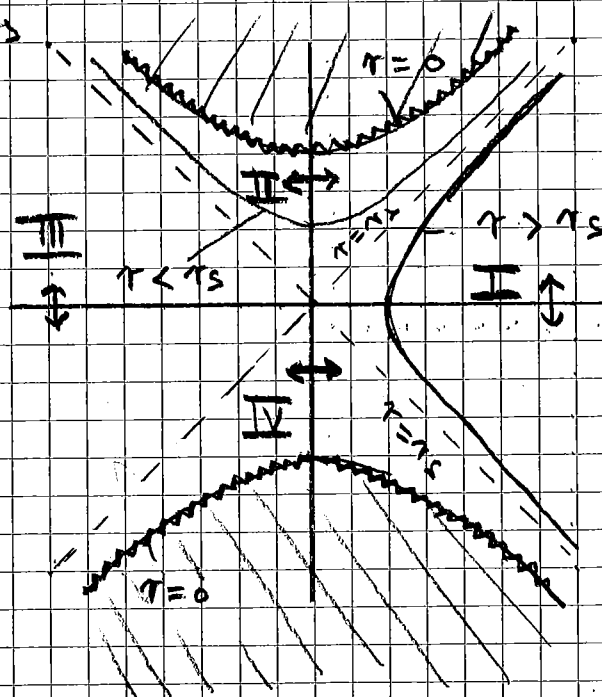
of the region from which the observer cannot receive any signals is called his future event horizon  $H^+$

The boundary

$$\partial(\text{III} \cup \text{IV}) = (\overline{\text{III} \cup \text{IV}}) - (\text{III} \cup \text{IV})^{\circ} \quad (11.7.28)$$

of the region to which the observer cannot send any signal is called his past event horizon  $H^-$

The Killing vector field  $K = \frac{\partial}{\partial x}$  (11.7.20) is somewhat analogous to the Killing vector field  $\frac{\partial}{\partial t}$  of staticity in the exterior Schwarzschild geometry. Worldlines of constant  $\xi$  here correspond to worldlines of constant  $r$  there; here  $\xi \neq 0$  corresponds to  $r < r_s$  there. The maximal analytic extension of exterior Schwarzschild is the Kruskal manifold that has a structure as follows



- I = ext. Schw. / 1
- II = black hole
- III = ext. Schw. / 2
- IV = white hole