

Sheet 6 : Solutions

Problem 1

$$g = \left(1 + \frac{2\phi}{c^2}\right) c dt \otimes c dt - \left(1 - \frac{2\phi}{c^2}\right) d\vec{x} \otimes d\vec{x} \quad (6.1.1)$$

$$\phi(\vec{x}) = -G \int \frac{\rho(\vec{x}')}{\|\vec{x} - \vec{x}'\|} d^3x'$$

We use spherical polar-coordinates for the \vec{x}' -integration, such that \vec{x} points along the pole-axis:

$$\vec{x} = r \vec{e}_z$$

$$\vec{x}' = r' (\sin\theta \cos\varphi \vec{e}_x + \sin\theta \sin\varphi \vec{e}_y + \cos\theta \vec{e}_z) \quad (6.1.2)$$

$$\leadsto \|\vec{x} - \vec{x}'\| = (r^2 + r'^2 - 2rr' \cos\theta)^{1/2} \quad (6.1.3)$$

$$\leadsto \phi(\vec{x}) = -G \rho_0 \int_{R_1}^{R_2} dr' r'^2 \int_0^{2\pi} d\varphi \int_{-1}^{+1} \frac{d\sigma}{[r^2 + r'^2 - 2rr'\sigma]^{1/2}} \quad (6.1.4)$$

where $\sigma = \cos\theta$

$$\begin{aligned}
& \int_{-1}^1 \frac{d\sigma}{[\tau^2 + \tau'^2 - 2\tau\tau'\sigma]^{1/2}} \\
&= \left(-\frac{1}{\tau\tau'} \right) [\tau^2 + \tau'^2 - 2\tau\tau'\sigma]^{1/2} \Big|_{-1}^1 \\
&= \left(-\frac{1}{\tau\tau'} \right) \left\{ [(\tau - \tau')^2]^{1/2} - [(\tau + \tau')^2]^{1/2} \right\} \\
&= \frac{1}{\tau\tau'} [|\tau + \tau'| - |\tau - \tau'|] \quad (6.1.5)
\end{aligned}$$

Since $\tau < R_1 < \tau' < R_2$ this is

$$\begin{aligned}
&= \frac{1}{\tau\tau'} [\tau + \tau' - (\tau' - \tau)] \\
&= \frac{2}{\tau'} \quad (\text{indep. of } \tau!) \quad (6.1.6)
\end{aligned}$$

Hence (6.1.4) becomes

$$\begin{aligned}
\phi(\vec{x}) &= -2\pi G \rho_0 \int_{R_1}^{R_2} dt' \frac{2}{\tau'} \tau'^2 \\
&= -4\pi G \rho_0 \frac{1}{2} (R_2^2 - R_1^2) \\
&= -\frac{4\pi}{3} (R_2^3 - R_1^3) \rho_0 G \frac{1}{2} \frac{3R_2^2 - R_1^2}{R_2^3 - R_1^3} \\
&= -GM \frac{3}{2} \frac{R_2^2 - R_1^2}{R_2^3 - R_1^3} \quad (6.1.7)
\end{aligned}$$

The essential observation is that this is a constant. (\rightarrow Faraday cage!)
The value is not really relevant for us.

Hence inside the inner sphere of $r=R$, the metric becomes

$$g = A^2 c dt \otimes c dt - B^2 d\vec{x} \otimes d\vec{x} \quad (6.1.8)$$

where

$$\left. \begin{aligned} A &= \left(1 + \frac{2\phi}{c^2}\right)^{1/2} \\ B &= \left(1 - \frac{2\phi}{c^2}\right)^{1/2} \end{aligned} \right\} (6.1.9)$$

and ϕ is the constant on the r.h.s of (6.1.7)

Rescaling coordinates

$$\left. \begin{aligned} t &\mapsto t' := A t \\ \vec{x} &\mapsto \vec{x}' := B \vec{x} \end{aligned} \right\} (6.1.10)$$

gives

$$g = c dt' \otimes c dt' - d\vec{x}' \otimes d\vec{x}' \quad (6.1.11)$$

= Minkowski metric.

Equation (6.1.8) shows

$$g_{\alpha\beta} = \eta_{\alpha\beta} + h_{\alpha\beta} \quad (6.1.12)$$

where the constant $h_{\alpha\beta}$ are

$$h_{00} = \frac{2\phi}{c^2}$$

$$h_{0a} = 0$$

$$h_{ab} = \delta_{ab} \frac{2\phi}{c^2}$$

} (6.1.13)

Under a gauge-transformation

$$h_{\alpha\beta} \mapsto h'_{\alpha\beta} := h_{\alpha\beta} + \partial_\alpha \Lambda_\beta + \partial_\beta \Lambda_\alpha$$

(6.1.14)

If we choose

$$\Lambda_\alpha = -\frac{\phi}{c^2} X^\alpha$$

(6.1.15)

$$\leadsto \partial_\alpha \Lambda_\beta + \partial_\beta \Lambda_\alpha = -\frac{2\phi}{c^2} \delta_{\alpha\beta} \quad (6.1.16)$$

Hence

$$h'_{\alpha\beta} = 0$$

(6.1.17)

so that the metric is gauge equivalent to the Minkowski metric.

Problem 2

$$\vec{h}(\vec{x}) = \frac{4G\rho_0}{c^3} \underbrace{\vec{\Omega} \times \int d^3x' \frac{\vec{x}'}{\|\vec{x} - \vec{x}'\|}}_{\vec{x} \frac{4\pi}{3} \int dt' \rho'} \quad (6.2.1)$$

Since we consider the case $r < r'$

Hence

$$\vec{h}(\vec{x}) = \frac{4G\rho_0}{c^3} (\vec{\Omega} \times \vec{x}) \frac{4\pi}{3} \frac{1}{2} (R_2^2 - R_1^2) \quad (6.2.2)$$

If we set $R_1 = 0$ and $R_2 = R$,
this becomes

$$\begin{aligned} \vec{h}(\vec{x}) &= \underbrace{\frac{4\pi}{3} R^3 \rho_0}_M \frac{2G}{c^2 R} \frac{1}{c} (\vec{\Omega} \times \vec{x}) \\ &= \underbrace{\frac{2GM}{c^2 R}}_{\text{dimensionless}} \frac{1}{c} (\vec{\Omega} \times \vec{x}) \quad (6.2.3) \end{aligned}$$

dimensionless

=: so-called "gravitational
radius"

The gravitomagnetic field is

$$\begin{aligned}
 \vec{B}(\vec{x}) &= -c(\vec{\nabla} \times \vec{h}) \\
 &= \frac{2GM}{c^2 R} (-\vec{\nabla} \times (\vec{\Omega} \times \vec{x})) \\
 &= \frac{2GM}{c^2 R} \left[-\vec{\Omega} \underbrace{(\vec{\nabla} \cdot \vec{x})}_3 + (\vec{\Omega} \cdot \vec{\nabla}) \vec{x} \right] \\
 &= -2 \frac{2GM}{c^2 R} \vec{\Omega} \quad (6.2.4)
 \end{aligned}$$

which is constant

[Note electromagnetic analogue:
Magnetic field inside a homogeneously
charged sphere that is rotating.]

In Lecture we have seen that a
gravitomagnetic field gives rise to a
term in the geodesic equation of
the form

$$\ddot{\vec{z}} = \dots + \dot{\vec{z}} \times \vec{B} \quad (6.2.5)$$

Corresponding to a Coriolis term
 $-2 \vec{\omega} \times \dot{\vec{z}}$ with

$$\vec{\omega} = -\frac{1}{2} \vec{B} = \frac{2GM}{c^2 R} \vec{\Omega} \quad (6.2.6)$$

$$\ddot{\vec{z}} = \dots + \frac{2GM}{c^2 R} 2 \vec{\Omega} \times \dot{\vec{z}} \quad (6.2.7)$$

For that to equal $2 \vec{\Omega} \times \dot{\vec{z}}$ we must have

$$\frac{2GM}{c^2 R} = 1 \quad (6.2.7)$$

We will later see that this is a very suggestive equation. It says that the gravitational radius of our mass distribution equals its Schwarzschild Radius.

$$R = R_S(M) := \frac{2GM}{c^2} \quad (6.2.8)$$

i.e. our mass-distribution is sufficiently compact to form a black hole (or: a closed universe).

$$\begin{aligned} \text{For } \rho_0 &= 10^{-29} \text{ g} \cdot \text{cm}^{-3} \\ &= 10^{-26} \text{ kg} \cdot \text{m}^{-3} \end{aligned} \quad (6.2.9)$$

We get from (6.2.7)

$$\frac{2G \rho_0 \frac{4\pi}{3} R^3}{c^2 R} = 1 \quad (6.2.10)$$

or

$$R = \frac{c}{2} \cdot \left[\frac{3}{2\pi G \rho_0} \right]^{1/2} \quad (6.2.11)$$

In SI-units (m, s, kg) have

$$\begin{aligned} R &= 1.5 \cdot 10^8 \left[\frac{3}{2\pi \cdot 6.67 \cdot 10^{-11} \cdot 10^{-26}} \right]^{1/2} \text{ m} \\ &= 1.27 \cdot 10^{26} \text{ m} \\ &= 13.41 \cdot 10^9 \text{ ly} \quad (6.2.12) \end{aligned}$$

$$[\text{ly} = \text{light-year} = 9.46 \times 10^{15} \text{ m.}]$$

The radius (6.2.12) is surprisingly close to the Hubble-Radius or

$$\begin{aligned} &c \times \text{Age of Universe} \\ &= c \cdot 13.7 \cdot 10^9 \text{ years} \\ &= 13.7 \text{ ly.} \end{aligned}$$

Problem 3

Formula (11.76) of the lecture-notes reads

$$\vec{\omega}_{TL}(\vec{x}) = \frac{2}{5} \frac{G}{c^2} M R^2 \frac{3(\vec{\Omega} \cdot \vec{n})\vec{n} - \vec{\Omega}}{r^3} \quad (6.3.1)$$

Here M = total mass of body

R = radius of body

$\vec{\Omega}$ = angular velocity

Applied to Earth

$$M = 5.972 \times 10^{24} \text{ kg}$$

$$R = 6.371 \times 10^6 \text{ m}$$

$$\Omega = 2\pi / \text{sidereal period}$$

$$= 2\pi / 23 \text{ h } 56 \text{ m } 4.1 \text{ s}$$

$$= 2\pi / 86164.1 \text{ s}$$

$$= 7.29 \cdot 10^{-5} \text{ s}^{-1}$$

(6.3.2)

We choose spherical polar coordinates with $\vec{\Omega} = \Omega \vec{e}_z$ pointing along polar axis. Since (6.3.1) only depends on r and $(\vec{\Omega} \cdot \vec{n}) = \Omega \cos \theta$ but not on azimuth φ . We can evaluate it for $\varphi = 0$ i.e. in the $y=0$ plane, i.e. the xz -plane. Then $\vec{n} = \sin \theta \vec{e}_x + \cos \theta \vec{e}_z$. Also, on the surface of the Earth $r = R$, so that

$$\vec{\omega}_{TL}(\theta) = \frac{2GM}{c^2 R} \cdot \frac{\Omega}{5} \cdot \left[3(\vec{e}_z \cdot \vec{h})\vec{h} - \vec{e}_z \right] \quad (6.3.3)$$

Introducing the "gravitational radius"

$$R_g := \frac{2GM}{c^2} \quad (6.3.4)$$

also known as "Schwarzschild-radius",

which for the Earth is

$$\begin{aligned} R_g^{\oplus} &= \frac{2GM_{\oplus}}{c^2} = \frac{2 \cdot 6.674 \cdot 10^{-11} \cdot 5.972 \cdot 10^{24}}{(2.99792)^2 \cdot 10^{16}} \text{ m} \\ &= \frac{2 \cdot 6.674 \cdot 5.972}{(2.99792)^2} \cdot 10^{-3} \text{ m} \\ &= 8.87 \cdot 10^{-3} \text{ m} = 8.87 \text{ mm} \quad (6.3.5) \end{aligned}$$

so that (R = geom. radius of Earth)

$$\frac{R_g^{\oplus}}{R} = \frac{8.87 \cdot 10^{-3}}{6.371 \cdot 10^6} = 1.4 \times 10^{-9}. \quad (6.3.6)$$

Hence the prefactor of (6.3.3) is

$$\frac{R_g^{\oplus}}{R} \frac{\Omega}{5} = 2 \times 10^{-14} \text{ s}^{-1} \quad (6.3.7)$$

The latitude dependent part of (6.3.3) is

$$\begin{aligned}
 & 3 (\vec{e}_z \cdot \vec{n}) \vec{n} - \vec{e}_z \\
 &= 3 \cos \theta (\sin \theta \vec{e}_x + \cos \theta \vec{e}_z) - \vec{e}_z \\
 &= 3 \sin \theta \cos \theta \vec{e}_x + (3 \cos^2 \theta - 1) \vec{e}_z \quad (6.3.8)
 \end{aligned}$$

Note that

$$3 \sin \theta \cos \theta = \frac{3}{2} \sin(2\theta) \quad (6.3.9)$$

and

$$\begin{aligned}
 3 \cos^2 \theta - 1 &= \frac{3}{2} [(\cos^2 \theta - \sin^2 \theta) \\
 &\quad + \cos^2 \theta + \sin^2 \theta] - 1 \\
 &= \frac{3}{2} \cos(2\theta) + \frac{1}{2} \quad (6.3.10)
 \end{aligned}$$

Hence

$$\begin{aligned}
 & 3 (\vec{e}_z \cdot \vec{n}) \vec{n} - \vec{e}_z \\
 &= \frac{3}{2} [\sin(2\theta) \vec{e}_x + \cos(2\theta) \vec{e}_z] + \frac{1}{2} \vec{e}_z \quad (6.3.11)
 \end{aligned}$$

which consists of a constant part $\frac{1}{2} \vec{e}_z$ and a θ -dependent part which rotates orthogonally with twice the polar angle θ from $\frac{3}{2} \vec{e}_z$ (for $\theta = 0$) to $-\frac{3}{2} \vec{e}_z$ (for $\theta = \frac{\pi}{2}$) and back to $\frac{3}{2} \vec{e}_z$ (for $\theta = \pi$).

For the surface of the Earth we get

$$\vec{\omega}_{TL}(\theta) = 10^{-14} \cdot \text{s}^{-1} \times \left\{ 3 [\sin(2\theta)\vec{e}_x + \cos(2\theta)\vec{e}_z] + \vec{e}_z \right\} \quad (6.3.12)$$

Wetzell is located at 49° northern latitude
 $\Rightarrow 90^\circ - \theta = 49^\circ \Rightarrow \theta = 41^\circ$. Hence

$$\|\vec{\omega}_{TL}(\theta = 41^\circ)\| \cong 3.3 \times 10^{-14} \text{ s}^{-1} \quad (6.3.13)$$

At Wetzell variations of the Earth rotation rate, i.e. variations of the length of a day can be detected with accuracy of 0.1 milliseconds per day. That is

$$\frac{\Delta T}{T} = \frac{10^{-4} \text{ s}}{86400 \text{ s}} = 1.16 \cdot 10^{-9} \quad (6.3.14)$$

As $\Omega = 2\pi/T$, have also

$$\left| \frac{\Delta \Omega}{\Omega} \right| = 1.16 \cdot 10^{-9} \quad (6.3.15)$$

$$\begin{aligned} \text{or } \Delta \Omega &= 7.29 \cdot 10^{-5} \text{ s}^{-1} \cdot 1.16 \cdot 10^{-9} \\ &= 8.46 \cdot 10^{-14} \text{ s}^{-1} \end{aligned} \quad (6.3.16)$$

According to

$$\Delta\varphi = \frac{8\pi A}{\lambda c} \Delta\Omega \quad (6.3.17)$$

with $A = 16 \text{ m}^2$ and $\lambda = 632 \text{ nm}$ this corresponds to amazing accuracy of

$$\begin{aligned} \Delta\varphi &= 2\pi \frac{4A}{\lambda c} \Delta\Omega \\ &= 2\pi \frac{64 \text{ m}^2}{6,3 \cdot 10^{-7} \cdot 3 \cdot 10^8} \Delta\Omega \\ &\approx 2\pi \cdot \frac{1}{3} \Delta\Omega \\ &= 2\pi \cdot 3 \cdot 10^{-14} \quad (6.3.18) \end{aligned}$$

Given that, and is already obvious from comparing (6.3.16) and (6.3.13), the ring-lens at Wettzell is about a factor

$$\frac{3,3}{8,46} \approx 0,4 \quad (6.3.19)$$

away from being able to detect $\vec{\omega}_{TL}$ and hence the gravito-magnetic field of the Earth.

Problem 4

Let $S \mapsto Z(s) \in M$ be the timelike world-line in Minkowski-space, parametrised by proper length

$$S = c\tau, \quad \tau = \text{proper time} \quad (6.4.1)$$

so that for $\dot{Z} = d/ds Z$ we have

$$\dot{Z} \cdot \dot{Z} = 1 \quad (6.4.2)$$

Where " \cdot " stands for the Minkowski inner-product. Clearly

$$\dot{Z} \cdot \ddot{Z} = 0$$

Let $S \in S T_x^1(M)$ be a vector field along the curve $Z(s)$ satisfying the constraint

$$S(s) \dot{Z}(s) = 0 \quad (6.4.3)$$

for all s .

The Fermi-derivative of a vector field S over Z is

$$F_Z S = \nabla_{\dot{Z}} S + \dot{Z} (\ddot{Z} \cdot S) - \ddot{Z} (\dot{Z} \cdot S) \quad (6.4.4)$$

If (6.4.3) holds then $F_Z S = 0$ is equivalent to

$$\nabla_{\dot{Z}} S = -\dot{Z} (\ddot{Z} \cdot S) \quad (6.4.5)$$

Where, in general, we have in comp.

$$(\nabla_{\dot{z}} S)^{\alpha} = \dot{S}^{\alpha} + \dot{z}^{\lambda} \Gamma_{\lambda \beta}^{\alpha} S^{\beta} \quad (6.4.6)$$

If we use an affine chart on Minkowski space we have $\Gamma_{\lambda \beta}^{\alpha} = 0$ and (6.4.5) turns into

$$\dot{S}^{\alpha} = -\dot{z}^{\alpha} (\ddot{z}_{\beta} S^{\beta}). \quad (6.4.7)$$

Since $S \cdot \dot{z} = 0$ there are only 3 independent components of S . Let K and K' denote the instantaneous rest-frame of the particle and the laboratory-frame, respectively, so that the four-velocity \dot{z} of the particle has components

$$\left. \begin{aligned} \dot{z}^{\alpha} &= (1, \vec{0}) \quad (\text{w.r.t. } K) \\ \dot{z}'^{\alpha} &= \gamma (1, \vec{\beta}) \quad (\text{w.r.t. } K') \end{aligned} \right\} (6.4.8)$$

where $\vec{\beta} = \vec{V}/c$ is the velocity/ c of K with respect to K' and $\gamma = (1 - \beta^2)^{-1/2}$.

Let (S^0, \vec{S}) and (S'^0, \vec{S}') be the components of S with respect to K and K' , respectively. The same pure boost (i.e. "relativum free") Lorentz transformation that maps $\dot{z}^{\alpha} = (1, \vec{0})$ to $\dot{z}'^{\alpha} = \gamma (1, \vec{\beta})$ also maps (S^0, \vec{S}) to (S'^0, \vec{S}') .

Now

$$\Lambda^{\alpha}_{\beta} \dot{z}^{\beta} = \dot{z}'^{\alpha} \quad (6.4.9)$$

where

$$\Lambda^{\alpha}_{\beta} = \begin{bmatrix} \gamma & \gamma \vec{\beta}^T \\ \gamma \vec{\beta} & E_3 + (\gamma - 1) \vec{h} \otimes \vec{h}^T \end{bmatrix} \quad (6.4.10)$$

is a pure boost in $\vec{\beta}$ -direction, where $\vec{h} = \vec{\beta} / \beta$. Since $\dot{z} \cdot S = 0$ have in K

$$\dot{z}'^{\alpha} S_{\alpha} = S_0 = 0 \Rightarrow S^0 = 0. \quad (6.4.11)$$

Hence

$$S^{\alpha} = (0, \vec{S}) \quad (6.4.12)$$

and

$$S'^{\alpha} = \Lambda^{\alpha}_{\beta} S^{\beta} \quad (6.4.13)$$

$$\begin{aligned} \Rightarrow S'^0 &= \Lambda^0_{\beta} S^{\beta} = \Lambda^0_a S^a \\ &= \gamma (\vec{\beta} \cdot \vec{S}) \end{aligned} \quad (6.4.14)$$

$$\begin{aligned} S'^a &= \Lambda^a_{\beta} S^{\beta} = \Lambda^a_b S^b \\ &= S^a + (\gamma - 1) n^a (\vec{h} \cdot \vec{S}) \end{aligned} \quad (6.4.15)$$

or

$$\vec{S}' = \vec{S} + (\gamma - 1) (\vec{S} \cdot \vec{n}) \vec{n} \quad (6.4.16)$$

with $\vec{n} = \vec{\beta} / \beta$

Alternatively, using $\gamma^2 = (1 - \beta^2)^{-1}$, hence

$$\beta^2 = 1 - \gamma^{-2}$$

$$\begin{aligned} \vec{S}' &= \vec{S} + \frac{\gamma - 1}{\beta^2} (\vec{S} \cdot \vec{\beta}) \vec{\beta} \\ &= \vec{S} + \frac{\gamma^2}{\gamma + 1} (\vec{S} \cdot \vec{\beta}) \vec{\beta} \end{aligned} \quad (6.4.17)$$

This shows that

$$S'^a = \left(\gamma (\vec{\beta} \cdot \vec{S}), \vec{S} + \frac{\gamma^2}{\gamma + 1} (\vec{S} \cdot \vec{\beta}) \vec{\beta} \right) \quad (6.4.18)$$

are the components of the spin-vector in the laboratory frame K' in terms of its three independent components \vec{S} in the instantaneous rest frame of the particle that is not related relative to the laboratory frame, i. e. related to it by a pure boost.

[Recall definition of a "pure boost" relative to a "frame" or "observer" (the notion of a "pure boost as such" does not exist): Let v be a timelike vector, "the observer", a pure boost relative to v is a Lorentz transformation that only moves points in the timelike plane $\text{Span}\{v, n\}$, where n is some spacelike vector that w.l.o.g. we can choose s.t. $v \cdot n = 0$, and pointwise fixes all points in the spacelike plane orthogonal to $\text{Span}\{v, n\}$. Such a pure boost is always of the form $\exp(n \otimes v \downarrow - v \otimes n \downarrow)$.]

Using the parametrization (6.4.8) and (6.4.18) we evaluate (6.4.7) in the laboratory frame

$$\dot{S}'^a = -\dot{Z}'^a \left(\dot{Z}'^b S'^b \right) \quad (6.4.19)$$

Note

$$\begin{aligned} \dot{\gamma} &= \frac{d}{ds} (1 - \vec{\beta}^2(s))^{-1/2} \\ &= \frac{1}{2} (1 - \vec{\beta}^2)^{-3/2} 2 \vec{\beta} \cdot \dot{\vec{\beta}} \\ &= \gamma^3 (\vec{\beta} \cdot \dot{\vec{\beta}}) \end{aligned} \quad (6.4.20)$$

and

$$\ddot{\mathbf{z}}'^2 = (\dot{\gamma}, \dot{\gamma} \vec{\beta} + \gamma \dot{\vec{\beta}}) \quad (6.4.21)$$

$$\begin{aligned} \curvearrowright \ddot{\mathbf{z}} \cdot \mathbf{S} &= \eta_{\alpha\beta} \ddot{\mathbf{z}}'^{\alpha} S'^{\beta} = \ddot{\mathbf{z}}'^1 S'^1 \\ &= \left(\dot{\gamma} \gamma (\vec{\beta} \cdot \vec{S}) - (\dot{\gamma} \vec{\beta} + \gamma \dot{\vec{\beta}}) \left(\vec{S} + \frac{\gamma^2}{\gamma+1} (\vec{S} \cdot \vec{\beta}) \vec{\beta} \right) \right) \\ &= \dot{\gamma} \gamma (\vec{\beta} \cdot \vec{S}) - \dot{\gamma} (\vec{\beta} \cdot \vec{S}) - \frac{\dot{\gamma} \gamma^2}{\gamma+1} \beta^2 (\vec{\beta} \cdot \vec{S}) \\ &\quad - \gamma (\dot{\vec{\beta}} \cdot \vec{S}) - \frac{\gamma^3}{\gamma+1} (\vec{S} \cdot \vec{\beta}) (\dot{\vec{\beta}} \cdot \vec{\beta}) \end{aligned}$$

[Using $\frac{\gamma^2}{\gamma+1} \beta^2 = \frac{\gamma^2-1}{\gamma+1} = \gamma-1$ we see that

the 3rd term cancels the first two]

$$= -\gamma \left[(\dot{\vec{\beta}} \cdot \vec{S}) + \frac{\gamma^2}{\gamma+1} (\vec{S} \cdot \vec{\beta}) (\dot{\vec{\beta}} \cdot \vec{\beta}) \right] \quad (6.4.22)$$

Hence (6.4.19) reads in full glory:

$$\left. \begin{aligned} & \left(\gamma (\vec{\beta} \cdot \vec{S}), \vec{S} + \frac{\gamma^2}{\gamma+1} (\vec{S} \cdot \vec{\beta}) \vec{\beta} \right) \\ & = (1, \vec{\beta}) \gamma^2 \left[\dot{\vec{\beta}} \cdot \vec{S} + \frac{\gamma^2}{1+\gamma} (\vec{S} \cdot \vec{\beta}) (\dot{\vec{\beta}} \cdot \vec{\beta}) \right] \end{aligned} \right\} (6.4.23)$$

which constitutes one equation for the time component and three equations for the space components. They are

$$(\gamma (\vec{\beta} \cdot \vec{S}))^\circ = \gamma^2 \left[\dot{\vec{\beta}} \cdot \vec{S} + \frac{\gamma^2}{\gamma+1} (\vec{S} \cdot \vec{\beta}) (\dot{\vec{\beta}} \cdot \vec{\beta}) \right] \quad (6.4.24)$$

$$\left(\vec{S} + \frac{\gamma^2}{\gamma+1} (\vec{S} \cdot \vec{\beta}) \vec{\beta} \right)^\circ = \vec{\beta} \gamma^2 [\dots] \quad (6.4.25)$$

$$= \vec{\beta} (\gamma (\vec{\beta} \cdot \vec{S}))^\circ \quad (6.4.26)$$

Here we used (6.4.24) to replace the right-hand side of (6.4.25) by a simpler expression (6.4.26). We will evaluate these equations in turn.

Evaluation of (6.4.24)

Using (6.4.20) for $\dot{\gamma}$, we have

$$\begin{aligned} (\gamma (\vec{\beta} \cdot \vec{S}))^\circ &= \gamma \dot{\vec{\beta}} \cdot \vec{S} + \gamma (\dot{\vec{\beta}} \cdot \vec{S}) \\ &\quad + \gamma^3 (\vec{S} \cdot \vec{\beta}) (\dot{\vec{\beta}} \cdot \vec{\beta}) \end{aligned} \quad (6.4.27)$$

and (6.4.24) is equivalent to

$$\begin{aligned} \gamma (\dot{\vec{\beta}} \cdot \vec{S}) + \gamma (\dot{\vec{\beta}} \cdot \vec{S}) + \gamma^3 (\vec{S} \cdot \vec{\beta}) (\dot{\vec{\beta}} \cdot \vec{\beta}) \\ = \gamma^2 \left[\dot{\vec{\beta}} \cdot \vec{S} + \frac{\gamma^2}{\gamma+1} (\vec{S} \cdot \vec{\beta}) (\dot{\vec{\beta}} \cdot \vec{\beta}) \right] \end{aligned}$$

$$\begin{aligned} \Leftrightarrow (\dot{\vec{\beta}} \cdot \vec{S}) &= (\gamma-1) (\dot{\vec{\beta}} \cdot \vec{S}) + \left(\frac{\gamma^3}{\gamma+1} - \gamma^2 \right) (\vec{S} \cdot \vec{\beta}) (\dot{\vec{\beta}} \cdot \vec{\beta}) \\ &= (\gamma-1) (\dot{\vec{\beta}} \cdot \vec{S}) - \frac{\gamma^2}{\gamma+1} (\vec{S} \cdot \vec{\beta}) (\dot{\vec{\beta}} \cdot \vec{\beta}) \end{aligned} \quad (6.4.28)$$

Evaluation of (6.4.26)

$$\begin{aligned}
 \dot{\vec{S}} &= \dot{\vec{\beta}} [\gamma (\vec{S} \cdot \vec{\beta})] \\
 &\quad - \left[\frac{\gamma}{\gamma+1} \gamma (\vec{S} \cdot \vec{\beta}) \dot{\vec{\beta}} \right] \\
 &= \left[1 - \frac{\gamma}{\gamma+1} \right] (\gamma (\vec{S} \cdot \vec{\beta})) \dot{\vec{\beta}} \\
 &\quad - \left(\frac{\gamma}{\gamma+1} \right) \gamma (\vec{S} \cdot \vec{\beta}) \dot{\vec{\beta}} \\
 &\quad - \frac{\gamma^2}{\gamma+1} (\vec{S} \cdot \dot{\vec{\beta}}) \vec{\beta}
 \end{aligned} \tag{6.4.29}$$

Using

$$\begin{aligned}
 \frac{\gamma}{\gamma+1} &= \gamma \frac{d}{d\gamma} \left[\frac{\gamma}{\gamma+1} \right] \\
 &= \gamma^3 (\dot{\vec{\beta}} \cdot \vec{\beta}) \underbrace{\left[\frac{1}{\gamma+1} - \frac{\gamma}{(\gamma+1)^2} \right]}_{1/(\gamma+1)^2} \\
 &= \frac{\gamma^3}{(\gamma+1)^2} (\dot{\vec{\beta}} \cdot \vec{\beta})
 \end{aligned} \tag{6.4.30}$$

We get

$$\begin{aligned}
 \dot{\vec{S}} &= \frac{\gamma}{\gamma+1} (\dot{\vec{S}} \cdot \vec{\beta}) \vec{\beta} + \frac{\gamma}{\gamma+1} (\dot{\vec{S}} \cdot \dot{\vec{\beta}}) \vec{\beta} \\
 &+ \frac{\gamma^3}{\gamma+1} (\dot{\vec{S}} \cdot \vec{\beta}) (\vec{\beta} \cdot \dot{\vec{\beta}}) \vec{\beta} \\
 &- \frac{\gamma^4}{(\gamma+1)^2} (\dot{\vec{S}} \cdot \vec{\beta}) (\dot{\vec{\beta}} \cdot \vec{\beta}) \vec{\beta} \\
 &- \frac{\gamma^2}{\gamma+1} (\dot{\vec{S}} \cdot \dot{\vec{\beta}}) \dot{\vec{\beta}}
 \end{aligned}
 \left. \begin{array}{l} \\ \\ \\ \end{array} \right\} \frac{\gamma^3}{(\gamma+1)^2} (\dot{\vec{S}} \cdot \vec{\beta}) (\dot{\vec{\beta}} \cdot \vec{\beta}) \vec{\beta}$$

(G.4.31)

Elimination of $(\dot{\vec{S}} \cdot \vec{\beta})$ via (G.4.28) in the final term gives

$$\begin{aligned}
 \dot{\vec{S}} &= \frac{\gamma}{\gamma+1} \left[(\gamma-1) (\dot{\vec{\beta}} \cdot \dot{\vec{S}}) - \frac{\gamma^2}{\gamma+1} (\dot{\vec{S}} \cdot \vec{\beta}) (\dot{\vec{\beta}} \cdot \vec{\beta}) \right] \vec{\beta} \\
 &+ \frac{\gamma}{\gamma+1} (\dot{\vec{S}} \cdot \dot{\vec{\beta}}) \vec{\beta} + \frac{\gamma^3}{(\gamma+1)^2} (\dot{\vec{S}} \cdot \vec{\beta}) (\dot{\vec{\beta}} \cdot \vec{\beta}) \vec{\beta} \\
 &- \frac{\gamma^2}{\gamma+1} (\dot{\vec{S}} \cdot \dot{\vec{\beta}}) \dot{\vec{\beta}}
 \end{aligned}$$

$$= \frac{\gamma^2}{\gamma+1} \left[(\dot{\vec{S}} \cdot \dot{\vec{\beta}}) \vec{\beta} - (\dot{\vec{S}} \cdot \vec{\beta}) \dot{\vec{\beta}} \right]$$

$$= \frac{\gamma^2}{\gamma+1} \dot{\vec{S}} \times (\vec{\beta} \times \dot{\vec{\beta}})$$

$$= \vec{\omega}_T \times \dot{\vec{S}}$$

Where $\vec{\omega}_T = \frac{\gamma^2}{\gamma+1} (\dot{\vec{\beta}} \times \vec{\beta})$

(G.4.32)

Note that we may replace $\dot{} = \frac{d}{ds} = \frac{1}{c} \frac{d}{d\tau}$ by $d/d\tau$ so that

$$\left. \begin{aligned} \frac{d\vec{S}}{d\tau} &= \vec{\omega}_T \times \vec{S} \\ \vec{\omega}_T &= \frac{\gamma^2}{\gamma+1} \left(\frac{d\vec{\beta}}{d\tau} \times \vec{\beta} \right) \end{aligned} \right\} (6.4.33)$$

Thus $\vec{\omega}_T$ is called the "Thomas frequency". It describes the proper-time angular frequency with which the spin vector precesses in a local rest frame that is non-rotating with respect to a fixed global inertial system (the "laboratory frame"), i.e. instantaneously related to the latter by a pure boost (at each instant).

Note that (6.4.32) gives back (6.4.28):

$$\begin{aligned} (\vec{\beta} \cdot \dot{\vec{S}}) &= \frac{\gamma^2}{\gamma+1} \left((\vec{S} \cdot \dot{\vec{\beta}}) \beta^2 - (\vec{S} \cdot \vec{\beta}) \dot{\beta} \right) \\ &= (\gamma-1) (\vec{S} \cdot \dot{\vec{\beta}}) - \frac{\gamma^2}{\gamma+1} (\vec{S} \cdot \vec{\beta}) \dot{\beta} \end{aligned} \quad (6.4.34)$$

Hence (6.4.32) is, in fact, equivalent to (6.4.23).