

Problem 1

$$1) \quad \sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\text{Clearly } \sigma_1^2 = \sigma_2^2 = \sigma_3^2 = E_2$$

$$\sigma_1 \cdot \sigma_2 = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix} = i \sigma_3$$

$$\sigma_2 \cdot \sigma_3 = \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix} = i \sigma_1$$

$$\sigma_3 \cdot \sigma_1 = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} = i \sigma_2$$

$$\Rightarrow \sigma_a \cdot \sigma_b = \delta_{ab} E_2 + i \epsilon_{abc} \sigma_c \quad (2.1.1)$$

$$2) \quad \text{Have } \dim_{\mathbb{C}}(\text{End}(\mathbb{C})) = 2 \times 2 = 4.$$

$\leadsto$  it suffices to show that

$\{E_2, \sigma_1, \sigma_2, \sigma_3\}$  are linearly independent. Now, if

$$\alpha E_2 + \beta^a \sigma_a = 0, \quad (2.1.2)$$

taking the trace gives, because of

$$\text{Trace}(\sigma_a) = 0, \quad 2\alpha = 0 \Leftrightarrow \alpha = 0. \quad (2.1.3)$$

Multiplication of (2.1.2) with  $\sigma_b$  gives, using (2.1.1):

$$\alpha \sigma_b + \beta^a \delta_{ab} E_2 + i \beta^c \epsilon_{abc} \sigma_c = 0 \quad (2.1.4)$$

Taking the trace gives

$$2 \beta^b = 0 \Leftrightarrow \beta^b = 0 \quad (2.1.5)$$

As this is true for any  $b \in \{1, 2, 3\}$ ,  
we get  $\vec{\beta} = \vec{0} \Leftrightarrow \{E_2, \vec{\sigma}\}$  are  
linearly independent.

3)

We write  $E_2 =: \sigma^0$  (just a name)  
and set

$$M = M \times \sigma^\lambda = \sum_{\lambda=0}^3 M_\lambda \sigma^\lambda \quad (2.1.6)$$

This we can do for any  $M \in \text{End}(\mathbb{C}^2)$   
Since  $\{\sigma^0, \vec{\sigma}\}$  span  $\text{End}(\mathbb{C}^2)$ , as  
just seen. Taking the trace gives

$$\text{Trace}(M) = 2 M_0, \quad \text{or}$$

$$M_0 = \frac{1}{2} \text{Trace}(M). \quad (2.1.7)$$

Now, using (2.1.1) we compute:

$$\begin{aligned} \sigma_a M \sigma^a &= \sigma_a (M_0 \sigma^0 + M_b \sigma^b) \sigma^a \\ &= 3 M_0 \sigma^0 + M_b (\sigma_a [\delta^{ba} E_2 + i \epsilon^{bac} \sigma^c]) \\ &= 3 M_0 \sigma^0 + M_b (\sigma^b + i \epsilon^{bac} i \epsilon^{acd} \sigma^d) \\ &= 3 M_0 \sigma^0 - M_b \sigma^b = 4 M_0 \sigma^0 - M \end{aligned}$$

$$\Rightarrow M = 2 \text{Trace}(M) E_2 - \sigma_a M \sigma^a \quad (2.1.8)$$

## Problem 2

S2.3

$$L = \bigoplus_{a=1}^N I_a$$

(2.2.1)

$L =$  semi-simple (no non-trivial abelian ideal)

$I_a =$  simple ideals

We wish to show that any simple ideal  $I \in L$  is one of the  $I$ 's.

So let's assume  $I \subset L$  is a simple ideal, then

$$[I, L] := \text{span} \{ [X, Y] : X \in I, Y \in L \} \\ \subset I$$

(2.2.2)

cannot be  $\{0\}$  because then

$$[I, I] \in [I, L] = \{0\}$$

(2.2.3)

and  $I$  would be an abelian ideal of  $L$ , in contradiction to  $L$  being semi simple. Hence  $[I, L] \neq \{0\} \subset I$  is itself an ideal of  $I \Rightarrow [I, L] = I$

From (2.2.1)

$$I = [I, L] = \bigoplus_{a=1}^N [I, I_a]$$

as  $I$  is simple only one summand

eg for  $a=i$ , can be non zero  $\Rightarrow I = [I, I_i]$

$=$  ideal in  $I_i$  (simple)  $\Rightarrow I = I_i$ .

Problem 3

$$1) \quad \exp(\vec{w} \cdot \vec{\sigma}), \quad \vec{w} \in \mathbb{C}^3$$

$$\det \exp(\vec{w} \cdot \vec{\sigma}) = \exp(\underbrace{\text{Trace}(\vec{w} \cdot \vec{\sigma})}_{=0})$$

$$= 1$$

$$\Rightarrow \exp(\vec{w} \cdot \vec{\sigma}) \in \text{SL}(2, \mathbb{C})$$

2.)

$$\exp(\vec{w} \cdot \vec{\sigma}) := \sum_{n=0}^{\infty} \frac{(\vec{w} \cdot \vec{\sigma})^n}{n!}$$

$$= \sum_{n=0}^{\infty} \frac{(\vec{w} \cdot \vec{\sigma})^{2n}}{(2n)!} + \sum_{n=0}^{\infty} \frac{(\vec{w} \cdot \vec{\sigma})^{2n+1}}{(2n+1)!}$$

From (2.1.1) we know

$$(\vec{w} \cdot \vec{\sigma})^2 = w^2 E_2 \quad (w^2 = \vec{w} \cdot \vec{w})$$

For  $\vec{w} \in \mathbb{C}^3 \setminus \{0\}$   $w$  may be zero,  $> 0$  or  $< 0$ .

1 Case:  $w^2 = 0$ 

$$\begin{aligned} \exp(\vec{w} \cdot \vec{\sigma}) &= E_2 + \vec{w} \cdot \vec{\sigma} \\ &= E_2 + b \cdot \vec{\sigma}_1 + c \cdot \vec{\sigma}_2 \end{aligned}$$

where  $\vec{w} = b + i c \vec{\tau}$ ,  $b, \vec{\tau} \in \mathbb{R}^3$

2. Case  $\vec{W}^2 = \Theta^2 \in \mathbb{C} \setminus \{0\}$ .

$$(\vec{W} \cdot \vec{\sigma})^2 = \vec{W}^2 E_2 = \Theta^2 E_2$$

$$\exp(\vec{W} \cdot \vec{\sigma}) = \sum_{n=0}^{\infty} \frac{(\vec{W} \cdot \vec{\sigma})^{2n}}{(2n)!} + \sum_{n=0}^{\infty} \frac{(\vec{W} \cdot \vec{\sigma})(\vec{W} \cdot \vec{\sigma})^{2n}}{(2n+1)!}$$

$$= E_2 \sum_{n=0}^{\infty} \frac{\Theta^{2n}}{(2n)!} + \frac{\vec{W} \cdot \vec{\sigma}}{\Theta} \sum_{n=0}^{\infty} \frac{\Theta^{2n}}{(2n+1)!}$$

$$= E_2 \cosh(\Theta) + \frac{\vec{W}}{\Theta} \cdot \vec{\sigma} \sinh(\Theta)$$

Subcase 2.1:  $\vec{W}^2 = \Theta^2 = -\alpha^2, \alpha \in \mathbb{R}_+$

$\Rightarrow \Theta = i\alpha$  (we shall choose that root)

$$\Rightarrow \exp(\vec{W} \cdot \vec{\sigma}) = \cos(\alpha) E_2 + i \vec{n} \cdot \vec{\sigma} \sin(\alpha)$$

$$\text{where } \vec{n} := \frac{\vec{W}}{\Theta}, \vec{n}^2 = 1.$$

Subcase 2.2:  $\vec{W}^2 = \Theta^2 = +\alpha^2, \alpha \in \mathbb{R}$

$$\Rightarrow \exp(\vec{W} \cdot \vec{\sigma}) = \cosh(\alpha) E_2 + \vec{n} \cdot \vec{\sigma} \sinh(\alpha)$$

In general  $\vec{W} = \vec{b} + i\vec{\tau}$

$$\vec{W}^2 = \|\vec{b}\|^2 - \|\vec{\tau}\|^2 + 2i \vec{b} \cdot \vec{\tau}$$

This is a mixture of a boost in  $\vec{b}$ -direction and a rotation around the  $\vec{\tau}$  axis, as we shall see in the Lecture.

Problem 4

1.)

$$[L, L] := \text{Span} \{ [X, Y] : X, Y \in L \} \quad (2.4.1)$$

is obviously a linear subspace that inherits the  $[\cdot, \cdot]$ -product under which it is closed:  $X, Y \in [L, L] \Rightarrow [X, Y] \in [L, L]$  (tautologically). The properties of  $[\cdot, \cdot]$  restricted to  $[L, L]$  follow from that of  $[\cdot, \cdot]$ .

2) If  $L$  is simple, since  $[L, L]$  is an ideal,  $[L, L] = \{0\}$  or  $[L, L] = L$ . If  $\dim(L) \neq 2$   $[L, L] = \{0\}$  is impossible, for otherwise any 1-dim. subspace of  $L$  would be a non-trivial ideal. Hence  $[L, L] = L$ .

$$3) \text{ From } L = \bigoplus_{\alpha=1}^N I_{\alpha} \quad (2.4.2)$$

$$\Rightarrow [L, L] = \bigoplus_{\alpha=1}^N [I_{\alpha}, I_{\alpha}]$$

$$= \bigoplus I_{\alpha}$$

(2.4.3)

Since  $[I_{\alpha}, I_{\alpha}] = I_{\alpha}$  by 2)

4) In a semi-direct product  $V \rtimes G$ , with  $G \subseteq \text{End}(V)$  we have

$$\text{Lie}(V \rtimes G) \cong V \times \text{Lie}(G) \quad (2.4.4)$$

with

$$[(\dot{a}, \dot{A}), (\dot{b}, \dot{B})] = (\dot{A}\dot{b} - \dot{B}\dot{a}, [\dot{A}, \dot{B}]) \quad (2.4.5)$$

If  $G$  is semisimple and hence perfect, sums of terms  $[\dot{A}, \dot{B}]$  give all of  $\text{Lie}(G)$ . For  $\text{Lie}(V \rtimes G)$  to be perfect sums of terms  $\dot{A}\dot{b}$ ,  $\dot{A} \in G$ ,  $\dot{b} \in V$  must give all of  $V$ . This is true if  $G \subseteq \text{End}(V)$  acts irreducibly on  $V$ , i.e.

$$\text{Span}\{\dot{A}\dot{b} : \dot{A} \in G, \dot{b} \in V\} = V \quad (2.4.6)$$

Problem 5

$$1) \quad U(n) = \{ A \in GL(\mathbb{C}^n) : \langle AX, AY \rangle = \langle X, Y \rangle \quad \forall X, Y \in \mathbb{C}^n \} \quad (2.5.1)$$

Let  $s \mapsto A(s)$  be  $C^1$ -curve in  $U(n)$  such that  $A(0) = \text{id}$ ,

$$\langle A(s)X, A(s)Y \rangle = \langle X, Y \rangle \quad (2.5.2)$$

$\frac{d}{ds} \Big|_{s=0}$  of (2.5.2) gives

$$\langle \dot{A}X, Y \rangle + \langle X, \dot{A}Y \rangle = 0 \quad \forall X, Y$$

$$\Leftrightarrow \dot{A}^t = -\dot{A}$$

$$\Rightarrow \text{Lie}(U(n)) = \{ X \in \text{End}(\mathbb{C}^n) : X^t = -X \} \quad (2.5.3)$$

$$2) \quad T: \text{Lie}(SL(2, \mathbb{R})) \rightarrow \text{Lie}(U(n)) \quad (2.5.4)$$

Lie-homomorphism

$$\text{we write } T(X^\pm) =: \hat{X}^\pm \quad \text{and} \quad T(H) = \hat{H}; \quad \text{then} \quad (2.5.5)$$

$$T([H, X^+]) = 2T(X^+) \quad \text{implies}$$

$$\hat{H}\hat{X}^+ - \hat{X}^+\hat{H} = 2\hat{X}^+$$

$$\begin{aligned} \rightarrow (\hat{X}^+)^2 &= \frac{1}{2} \hat{X}^+ [\hat{H}, \hat{X}^+] \\ &= \frac{1}{2} (\hat{X}^+ \hat{H} \hat{X}^+ - (\hat{X}^+)^2 \hat{H}) \end{aligned} \quad (2.5.6)$$



Hence

$$\begin{aligned} & \text{Trace}[(\hat{X}^+)^2] \\ &= \frac{1}{2} \text{Trace}(\hat{X}^+ \hat{H} \hat{X}^+ - \hat{X}^+ \hat{X}^+ \hat{H}) = 0 \end{aligned}$$

cyclic property  
of trace

$$\text{Hence } \text{Trace}(\hat{X}^+)^2 = 0 \quad (2.5.7)$$

But since  $\hat{X}^+$  is anti-hermitean

$$\text{Trace}(\hat{X}^+)^2 = - \sum_{\substack{a,b \\ = 1 \\ = n}}^n |\hat{X}^+_{ab}|^2 \leq 0 \quad (2.5.8)$$

$$\text{and } = 0 \iff \hat{X}^+ = 0$$

$$\text{Hence } X^+ \in \text{Kernel}(T). \quad (2.5.9)$$

As  $\text{Kernel } T \subseteq \text{Lie}(SL(2, \mathbb{R}))$  is an ideal, which, as just seen, contains  $X^+$ , it must be identical to all of  $\text{Lie}(SL(2, \mathbb{R}))$  by the fact that  $\text{Lie}(SL(2, \mathbb{R}))$  is simple (Sheet 1, Problem 6).

$$\Rightarrow \text{Kernel}(T) = \text{Lie}(SL(2, \mathbb{R}))$$

$$\Leftrightarrow T = 0 \quad (\text{the trivial map with image } 0). \quad (2.5.10)$$

3) Let

S2.10

$$D: SL(2, \mathbb{R}) \rightarrow U(n) \quad (2.5.11)$$

be a group homomorphism (a unitary representation). Then

$$D_*: \text{Lie}(SL(2, \mathbb{R})) \rightarrow \text{Lie}(U(n)) \quad (2.5.12)$$

is a homomorphism of Lie-algebras, where  $D_*$  is the differential of  $D$  at the group identity. But we have just seen that  $D_* = 0$ . Now, we have

$$\left. \frac{d}{ds} \right|_{s=0} D(\exp(sX)) = D_*(X) = 0 \quad (2.5.13)$$

$\rightarrow$   $D$  maps all elements in the image of the exponential map to the same element in  $U(n)$ , i.e. the identity.

As  $SL(2, \mathbb{R})$  is connected, and any element of a connected Lie group is the finite product of elements in the image of  $\exp$ , we have

$$\begin{aligned} D(A) &= D(\exp(X_1) \cdots \exp(X_n)) \\ &= D(\exp(X_1)) \cdots D(\exp(X_n)) = e \end{aligned} \quad (2.5.14)$$

$\Rightarrow$   $D$  is trivial. (Same for  $SL(2, \mathbb{C})$ ).

Problem 6

$$\begin{aligned} \mathcal{O}(V, W) &:= \{ A \in GL(V) : W(Av, Aw) \\ &= W(v, w), \forall v, w \in V \} \end{aligned} \quad (2.6.1)$$

1.) Let  $s \mapsto A(s)$  be  $C^1$ -curve in  $\mathcal{O}(V, W)$  with  $A(0) = e$ , then

$$W(A(s)v, A(s)w) = W(v, w) \quad (2.6.2)$$

$\frac{d}{ds} \Big|_{s=0}$  of that gives

$$W(\dot{A}v, w) + W(v, \dot{A}w) = 0 \quad (2.6.3)$$

hence

$$\begin{aligned} \text{Lie}(\mathcal{O}(V, W)) &= \{ X \in \text{End}(V) : W(Xv, w) \\ &= -W(v, Xw), \forall v, w \in V \} \end{aligned} \quad (2.6.4)$$

2.)  $\{ e_a \mid a=1, \dots, n \}$ ,  $W_{ab} := W(e_a, e_b)$   
then

$$W(X e_a, e_b) = -W(e_a, X e_b) \quad (2.6.5)$$

$$\Leftrightarrow X^c_a W_{cb} = -X^c_b W_{ac} \quad (2.6.6)$$

We set

$$W(v, w) = \varepsilon W(w, v) \quad (2.6.7)$$

$$\text{where } \varepsilon = \pm 1 \quad (2.6.8)$$

and also define

$$X^c_a W_{cb} =: X_{ba} \quad (2.6.9)$$

Then (2.6.6) is equivalent to

$$\begin{aligned} X_{ba} &= -X^c{}_b W_{ac} \\ &= -\varepsilon X^c{}_b W_{ca} \\ &= -\varepsilon X_{ab} \end{aligned} \quad (2.6.10)$$

or

$$X_{ab} = -\varepsilon X_{ba} \quad (2.6.11)$$

3)  $\{\theta^a \mid a=1, \dots, n\}$  dual basis to  $\{e_a \mid a=1, \dots, n\}$ , s.t.

$$\theta^a(e_b) = \delta^a{}_b \quad (2.6.12)$$

$$M_{ab} := e_a \otimes \theta_b - \varepsilon e_b \otimes \theta_a$$

$$\text{with } \theta_a := W_{ab} \theta^b. \quad (2.6.13)$$

$$\begin{aligned} \text{Have } M_{ab} &= -M_{ba} \text{ for } \varepsilon = +1 \\ &= +M_{ba} \text{ for } \varepsilon = -1 \end{aligned} \quad \left. \vphantom{\begin{aligned} \text{Have } M_{ab} &= -M_{ba} \text{ for } \varepsilon = +1 \\ &= +M_{ba} \text{ for } \varepsilon = -1 \end{aligned}} \right\} (2.6.14)$$

i.e.  $\frac{1}{2}n(n-1)$  vectors for  $\varepsilon = +1$  and  $\frac{1}{2}n(n+1)$  vectors for  $\varepsilon = -1$ .

They are linearly independent; (or let

$$e^c = W^{ca} e_a \text{ with } W^{ac} W_{bc} = \delta^a{}_b,$$

$$\text{then } \theta_a(e^b) = W_{ac} \theta^c(W^{bd} e_d) = \delta_a^b.$$

Hence, if for  $X^{ab} \in \mathbb{R}$ ,  $X^{ab} = -\varepsilon X^{ba}$ ,

$$\sum_{a,b} X^{ab} M_{ab} = 0 \quad (2.6.15)$$

application to  $e^c$

$$\sum (X^{ab} M_{ab}) (e^c)$$

$$= \sum X^{ab} (e_a \delta_b^c - \varepsilon e_b \delta_a^c)$$

$$= X^{ac} e_a - \varepsilon X^{cb} e_b = 2 X^{ac} e_a$$

$$= 0 \iff X^{ac} = 0 \text{ for all } a \quad (2.6.16)$$

and the given  $c$ . But since the argument can be repeated for any  $c$  we get  $X^{ab} = 0 \quad \forall a, b \in \{1, \dots, n\}$ .

$\Rightarrow \{M_{ab}\}$  are linearly independent and of right number  $\Rightarrow$  basis.

It remains to show that  $M_{ab} \in \text{Lie}(\mathcal{O}(V|W))$ . Hence we need to show that

$$W(M_{ab} e_c, e_d) = -W(e_c, M_{ab} e_d) \quad (2.6.17)$$

The left-hand side is

$$W(e_a W_{bc} - \varepsilon e_b W_{ac}, e_d)$$

$$= W_{ad} W_{bc} - \varepsilon W_{ac} W_{bd}$$

The right hand side is

$$- [W(e_c, e_a W_{bd} - \varepsilon e_b W_{ad})]$$

$$= - [W_{ca} W_{bd} - \varepsilon W_{cb} W_{ad}]$$

$$= -\varepsilon' W_{ac} W_{bd} + W_{bc} W_{ad} \quad (2.6.18)$$

Hence both sides coincide.

4.)

$$[M_{ab}, M_{cd}]$$

$$= (e_a \otimes \theta_b - \varepsilon e_b \otimes \theta_a) (e_c \otimes \theta_d - \varepsilon e_d \otimes \theta_c) \\ - (a \leftrightarrow c) (b \leftrightarrow d)$$

$$= \frac{W_{bc} e_a \otimes \theta_d}{1} + \frac{W_{ad} e_b \otimes \theta_c}{2} \\ - \frac{\varepsilon W_{ac} e_b \otimes \theta_d}{3} - \frac{\varepsilon W_{bd} e_a \otimes \theta_c}{4} \\ - \frac{W_{da} e_c \otimes \theta_b}{2} - \frac{W_{cb} e_d \otimes \theta_a}{1} \\ + \frac{\varepsilon W_{ca} e_d \otimes \theta_b}{3} + \frac{\varepsilon W_{db} e_c \otimes \theta_a}{4}$$

$$= W_{bc} (e_a \otimes \theta_d - \varepsilon e_d \otimes \theta_a) \\ + W_{ad} (e_b \otimes \theta_c - \varepsilon e_c \otimes \theta_b) \\ - \varepsilon W_{ac} (e_b \otimes \theta_d - \varepsilon e_d \otimes \theta_b) \\ - \varepsilon W_{bd} (e_a \otimes \theta_c - \varepsilon e_c \otimes \theta_a)$$

$$= W_{bc} M_{ad} + W_{ad} M_{bc}$$

$$- \varepsilon W_{ac} M_{bd} - \varepsilon W_{bd} M_{ac}$$

Problem 7

Consider  $G \subseteq GL(V)$  and

$$IG := V \rtimes G \quad (2.7.1)$$

$$\text{s.t. } (a, A)(b, B) = (a + Ab, AB), \quad (2.7.2)$$

$$\text{then } (a, A)^{-1} = (-A^{-1}a, A^{-1}) \quad (2.7.3)$$

$$\begin{aligned} 1.) \quad & (a, A)(b, B)(a, A)^{-1} \\ &= (a + Ab, AB)(-A^{-1}a, A^{-1}) \\ &= (a + Ab - ABA^{-1}a, ABA^{-1}). \end{aligned} \quad (2.7.4)$$

If  $b$  and  $B$  depend on parameter  $s$  ( $a$  and  $A$  are constant), then  $\frac{d}{ds}|_{s=0}$  leads to

$$\begin{aligned} \text{Ad}_{(a, A)}(\dot{b}, \dot{B}) &= (A\dot{b} - A\dot{B}A^{-1}a, A\dot{B}A) \\ &= (A\dot{b} - \text{Ad}_A(\dot{B})(a), \text{Ad}_A(\dot{B})) \end{aligned} \quad (2.7.5)$$

This is the adjoint representation of  $IG$  on its Lie-algebra,  $\text{Lie}(IG)$ ; see below. If we now consider a curve  $t \mapsto (a(t), A(t))$  with  $a(0) = 0$ ,  $A(0) = e$  (note:  $e$  is the identity in the ambient group  $V$ ), we can

take the derivative  $\frac{d}{dt}|_{t=0}$  of (2.7.5).

Note that

$$\frac{d}{dt}|_{t=0} A \dot{B} A^{-1} a = \dot{B} \hat{a} \quad (2.7.6)$$

(all other terms vanish due to  $a(0)=0$ ),  
so that

$$\text{ad}(\dot{a}, \dot{A})(\dot{b}, \dot{B}) = (\dot{A} \dot{b} - \dot{B} \dot{a}, [\dot{A}, \dot{B}]). \quad (2.7.7)$$

This is what we already used in  
(2.4.5).



## Problem 8

S2.17

From (2.7.5) we read off, setting  $b = x$  and  $\dot{B} = X$ ,

$$\text{Ad}_{(a, A)}(x, X) = (Ax - \text{Ad}_A(X)a, \text{Ad}_A(X)) \quad (2.8.1)$$

If  $(\sigma, \Sigma) \in \text{Lie}(IG)$ , so that

$$\begin{aligned} (\sigma, \Sigma)(y, y) &= \sigma(y) + \Sigma(y) \\ &= \sigma_a y^a + \Sigma_a{}^b y^a{}_b \end{aligned} \quad (2.8.2)$$

then we can compute

$$\begin{aligned} &\left\{ \text{Ad}_{(a, A)}^* (\sigma, \Sigma) \right\} (x, X) \\ &:= (\sigma, \Sigma) \left( \text{Ad}_{(a, A)}^{-1} (x, X) \right) \\ &= (\sigma, \Sigma) \text{Ad}_{(-A^{-1}a, A^{-1})} (x, X) \\ &= (\sigma, \Sigma) \left( A^{-1}x - \text{Ad}_{A^{-1}}(X)(-A^{-1}a), \text{Ad}_{A^{-1}}(X) \right) \\ &= (\sigma, \Sigma) \left( A^{-1}x + A^{-1}Xa, A^{-1}XA \right) \\ &= \sigma(A^{-1}x) + \sigma(A^{-1}Xa) + \Sigma(A^{-1}XA) \\ &= \sigma'(x) + \Sigma'(X) \end{aligned} \quad (2.8.3)$$

$$\Leftrightarrow \sigma' = A^* \sigma \quad (:= \sigma \circ A^{-1}) \quad (2.8.4)$$

$$\Sigma' = \text{Ad}_A^* \Sigma + A^* \sigma \otimes a \quad (2.8.5)$$

In case  $G$  is a subgroup of  $GL(V)$  the Lie-algebra  $Lie(G)$  is a linear subspace of  $End(V)$ . The element  $X$  in (2.8.3) is then from

$$X \in Lie(G) \subset End$$

and

$$\Sigma(X) = \Sigma(A^{-1}XA) + \sigma(A^{-1}Xa) \quad (2.8.6)$$

for all  $X \in Lie(G)$ .

$$\text{If } P: End(V) \rightarrow Lie(G) \quad (2.8.7)$$

is a projection map, then (2.8.6) implies

$$\Sigma' = Ad^*A \Sigma + \underbrace{P^*(A^* \sigma \otimes a)}_{(A^* \sigma \otimes a) \circ P} \quad (2.8.8)$$

For example, if  $G = O(V, W)$ , so that

$$Lie(G) = \{ X \in End(V) : W(XV, W) + W(V, XW) = 0 \quad \forall r, w \in V \} \quad (2.8.9)$$

$$\text{with } W(V, W) = \varepsilon W(W, V) \quad (2.8.10)$$

$$\text{and } W(V, \cdot) = W \downarrow (V) \quad (2.8.11)$$

(index lowering),

$$\text{have } W \downarrow (V)(W) = V(W \downarrow W) = \varepsilon W \downarrow (W)(V) \quad (2.8.12)$$

$$= \varepsilon V(W \downarrow (W))$$

Hence

$$\omega_{\downarrow} : V \rightarrow V^* \quad (2.8.13)$$

$$\omega_{\uparrow} := (\omega_{\downarrow})^{-1} : V^* \rightarrow V \quad (2.8.14)$$

$$\omega_{\downarrow}^T : V^{**} \cong V \rightarrow V^* \quad (2.8.15)$$

with

$$\omega_{\downarrow}^T = \varepsilon \omega_{\downarrow} \quad (2.8.16)$$

$$\omega_{\uparrow}^T = \varepsilon \omega_{\uparrow} \quad (2.8.17)$$

Then

$$\omega(Xv, w) + \omega(v, Xw) = 0$$

$$\Leftrightarrow \omega_{\downarrow} \circ X(v)(w) + \omega_{\downarrow}(v)(Xw) = 0$$

$$\Leftrightarrow \omega_{\downarrow} \circ X + X^T \circ \omega_{\downarrow} = 0$$

$$\Leftrightarrow X + \omega_{\uparrow} \circ X^T \circ \omega_{\downarrow} = 0 \quad (2.8.18)$$

This is the linear relation  $X \in \text{End}(V)$  has to satisfy in order to be in  $\text{Lie}(G)$ .

Consider the two linear maps

$$P_{\pm} : \text{End}(V) \rightarrow \text{End}(V)$$

$$X \mapsto P_{\pm}(X) := \frac{1}{2}(X \pm \omega_{\uparrow} \circ X^T \circ \omega_{\downarrow})$$

Have

$$P_+ + P_- = \text{id} |_{E \cap W(v)} \quad (2.8.20)$$

$$P_{\pm} P_{\pm}(X) = P_{\pm}^2(X)$$

$$= P_{\pm} \left( \frac{1}{2} (X \pm W_{\uparrow} \circ X^T \circ W_{\downarrow}) \right)$$

$$= \frac{1}{4} [ X \pm W_{\uparrow} \circ X^T \circ W_{\downarrow}$$

$$\pm W_{\uparrow} (X \pm W_{\uparrow} \circ X^T \circ W_{\downarrow})^T \circ W_{\downarrow} ]$$

$$= \frac{1}{4} [ X \pm 2 W_{\uparrow} \circ X^T \circ W_{\downarrow}$$

$$+ W_{\uparrow} (W_{\downarrow}^T \circ X \circ W_{\uparrow}^T) \circ W_{\downarrow} ]$$

$$\underbrace{\begin{array}{c} \text{"} \\ E W_{\downarrow} \end{array} \quad \begin{array}{c} \text{"} \\ E W_{\uparrow} \end{array}}_X$$

$$= P_{\pm}(X)$$

(2.8.21)

Similarly

$$P_+ \circ P_-(X) = P_- \circ P_+(X) = 0 \quad (2.8.22)$$

Hence  $P_{\pm}$  are projection operators  
and

$$\text{Lie}(\mathfrak{g}) = \text{Ker}(P_+) = \text{Image}(P_-) \quad (2.8.23)$$

Applied to (2.8.8) with  $\mathcal{P} = \mathcal{P}_-$   
we get

$$\text{Ad}^*(a(A)) (\sigma, \Sigma) = (\sigma', \Sigma') \quad (2.8.24)$$

where

$$\sigma' = A^* \sigma \quad (2.8.25)$$

$$\Sigma' = \text{Ad}_A^* (\Sigma + \mathcal{P}_-^* (A^* \sigma \otimes \sigma)) \quad (2.8.26)$$

For example, for the ordinary orthogonal group with respect to euclidean metric  $\mathcal{P}_-$  is just the antisymmetrisation in the tensor product.