

IRREDUCIBLE REPRESENTATIONS OF A SEMI-SIMPLE LIE ALGEBRA

The method with which we found the finite-dimensional irreps of $\mathfrak{sl}(3, \mathbb{C})$, or $\mathfrak{su}(3)$, respectively, can immediately be generalized to any semi-simple Lie algebra. This yields a procedure in eight steps, which I will sketch here very briefly. The semi-simple Lie algebra is denoted by \mathfrak{g} .

- [I] **Cartan subalgebra.** Find the maximal Abelian subalgebra $\mathfrak{h} \subset \mathfrak{g}$.
- [II] **Cartan decomposition.** Perform the Cartan decomposition $\mathfrak{g} = \mathfrak{h} \oplus \left(\bigoplus_{\alpha \in R} \mathfrak{g}_\alpha \right)$ for the adjoint representation, where the *root spaces* \mathfrak{g}_α are defined by the condition

$$\forall H \in \mathfrak{h}, \forall X \in \mathfrak{g}_\alpha : \text{ad}(H)(X) = \alpha(H) X$$

for $\alpha \in R \subset \mathfrak{h}^*$, the set of the *roots* of \mathfrak{g} . We have:

- (1) $\dim \mathfrak{g}_\alpha = 1$;
- (2) $\text{rank} \mathfrak{g} \equiv \text{rank} \Lambda_R = \dim \mathfrak{h}$ with $\Lambda_R = \text{span}_{\mathbb{Z}} R$ the *root lattice*;
- (3) $\alpha \in R \iff -\alpha \in R$.

Let V be a finite-dimensional irrep of \mathfrak{g} . Perform the Cartan decomposition for V analogously, i.e. decompose $V = \bigoplus_{\alpha \in W(V)} V_\alpha$, where the *weight spaces* V_α are defined by the condition

$$\forall H \in \mathfrak{h}, \forall v \in V_\alpha : H(v) = \alpha(H) v$$

for $\alpha \in W(V) \subset \mathfrak{h}^*$, the set of the *weights* of the representation V . We have:

- (1) $\dim V_\alpha = \text{mult}(\alpha)$ in the representation V ;
- (2) the root spaces act on the V_α in such a way that $\mathfrak{g}_\beta : V_\alpha \rightarrow V_{\alpha+\beta}$ for all $\beta \in R$. Then, obviously, it is true that $\forall \alpha, \alpha' \in W(V) : \alpha - \alpha' \in \Lambda_R$.

- [III] **Root subalgebras.** Find for each root α the corresponding subalgebra $\mathfrak{s}_\alpha = \mathfrak{g}_\alpha \oplus \mathfrak{g}_{-\alpha} \oplus [\mathfrak{g}_\alpha, \mathfrak{g}_{-\alpha}] \cong \mathfrak{sl}(2, \mathbb{C})$. we have:

- (1) $[\mathfrak{g}_\alpha, \mathfrak{g}_{-\alpha}] \neq 0$, such that $[\mathfrak{g}_\alpha, \mathfrak{g}_{-\alpha}] \subset \mathfrak{h}$, $\dim[\mathfrak{g}_\alpha, \mathfrak{g}_{-\alpha}] = 1$;
- (2) $[[\mathfrak{g}_\alpha, \mathfrak{g}_{-\alpha}], \mathfrak{g}_\alpha] \neq 0$, so that one can find generators, which satisfy the standard Lie brackets of $\mathfrak{sl}(2, \mathbb{C})$. In particular, there exists a $H_\alpha \in [\mathfrak{g}_\alpha, \mathfrak{g}_{-\alpha}]$ with $\alpha(H_\alpha) = 2$.

- [IV] **Weight lattice.** Make use of the rather simple representation theory of the $\mathfrak{s}_\alpha \cong \mathfrak{sl}(2, \mathbb{C})$ in order to construct the lattice $\Lambda_W = \{\beta \in \mathfrak{h}^* : \beta(H_\alpha) \in \mathbb{Z} \forall \alpha \in R\}$, since all eigen values of H_α have to be integers. Obviously, for any finite-dimensional irrep V is the set of weights $W(V) \subset \Lambda_W$. In particular, $R \subset \Lambda_W$, therefore $\Lambda_R \subset \Lambda_W$ is a sublattice with finite index.

- [V] **Weyl group.** Use the fact that the weights of representations of $\mathfrak{s}_\alpha \cong \mathfrak{sl}(2, \mathbb{C})$ possess a reflection symmetry by introducing the reflections W_α ,

$$W_\alpha(\beta) = \beta - 2 \frac{\beta(H_\alpha)}{\alpha(H_\alpha)} \alpha = \beta - \beta(H_\alpha) \alpha,$$

which map the hyperplanes $\Omega_\alpha = \{\beta \in \mathfrak{h}^* : \langle H_\alpha, \beta \rangle = 0\}$ into themselves, and reflect the lines $\mathbb{C}\alpha$ into themselves, i.e. $W_\alpha(\alpha) = -\alpha$. The group \mathfrak{W} generated from the W_α , $\alpha \in R$, is called *Weyl group*. In particular, one has that the set of weights of a representation is invariant under the Weyl group, i.e. $\mathfrak{W}(W(V)) = W(V)$.

- [VI] **Killing form.** Define the Killing form $g(X, Y) = \text{tr}(\text{ad}(X) \circ \text{ad}(Y))$ as Scalar product on \mathfrak{g} , thus also on $\mathfrak{h} \subset \mathfrak{g}$, which naturally extends to a scalar product on $\mathfrak{h}^* \cong \mathfrak{h}$. The Weyl group is then nothing else than the orthogonal group, $\mathfrak{W} = O(\Lambda_W)$, i.e. $g(W_\alpha(\beta), W_\alpha(\beta')) = g(\beta, \beta')$ for all $W_\alpha \in \mathfrak{W}$, $\beta, \beta' \in \Lambda_W \subset \mathfrak{h}^*$. With respect to this scalar product the line $\mathbb{C}\alpha$ and the hyperplane Ω_α are orthogonal, i.e. $\alpha \perp \Omega_\alpha$. The scalar product $g(\cdot, \cdot)$ is positive definite on \mathfrak{h} .

- [VII] **Highest weights and highest weight vectors.** Choose a direction in \mathfrak{h}^* by choosing a real linear function $\ell : \Lambda_R \rightarrow \mathbb{R}$, which divides the roots into two equally sized subsets $R = R^+ \cup R^-$. Here, $R^+ = \{\alpha \in R : \ell(\alpha) > 0\}$ is the set of *positive roots*, and analogously $R^- = \{\alpha \in R : \ell(\alpha) < 0\}$ is the set of *negative roots*. For a representation V of \mathfrak{g} we call a vector $v \in V$, which is eigen vector to all $H \in \mathfrak{h}$, and which simultaneously is in the kernel of all root spaces of the positive roots, a *highest weight vector*, i.e. $v \in V$ is a highest weight vector

with *highest weight* or *dominant weight* $\alpha \iff H(v) = \alpha(H)v$ for all $H \in \mathfrak{h}$, and $\mathfrak{g}_\alpha(v) = 0$ for all $\alpha \in R^+$. We have:

- (1) Any finite-dimensional representation V of \mathfrak{g} possesses a highest weight vector;
- (2) To any finite dimensional representation V of \mathfrak{g} with highest weight vector $v \in V$ is the subrepresentation $W = \text{span}\{v, \mathfrak{g}_\alpha(v), \mathfrak{g}_\alpha \mathfrak{g}_{\alpha'}(v), \dots : \alpha, \alpha', \dots \in R^-\} \subset V$ irreducible;
- (3) Any finite-dimensional irrep V of \mathfrak{g} has (up to normalization) a unique highest weight vector.

The so-called (positive) *primitive* or *simple roots* are those positive roots, which are not the sum of two other positive roots, i.e. $R_p^+ = \{\alpha \in R^+ : \alpha \neq \alpha' + \alpha'' \text{ for } \alpha', \alpha'' \in R^+\}$. Analogously one defines negative simple roots R_p^- . Then, the above definition of $W \subset V$ simplifies to $W = \text{span}\{v, \mathfrak{g}_\alpha(v), \mathfrak{g}_\alpha \mathfrak{g}_{\alpha'}(v), \dots : \alpha, \alpha', \dots \in R_p^-\}$.

The (*closed*) *Weyl chamber* \mathcal{W} is the region in \mathfrak{h}^* , within which all possible highest weights must reside. It is defined as $\mathcal{W} = \{\alpha \in \text{span}_{\mathbb{R}} R : \alpha(H_\gamma) \geq 0 \forall \gamma \in R^+\}$. An equivalent definition is as the closure of a connected component of the complement of the union of the hyperplanes Ω_α .

[IIX] Classification of irreps. Now, we have everything in place to completely describe all finite-dimensional irreps of a semi-simple Lie algebra \mathfrak{g} .

THEOREM: For any $\alpha \in \mathcal{W} \cap \Lambda_W$ there is exactly one finite-dimensional irrep Γ_α with α its highest weight. Let \mathcal{C} denote the closure of the open convex hull, whose vertices are given by the images of α under the action of the Weyl group \mathfrak{W} . Then, the set of weights of the irrep Γ_α are given by $W(\Gamma_\alpha) = \{\beta \in \Lambda_W \cap \mathcal{C} : \beta - \alpha \in \Lambda_R\}$. Let the positive simple roots be labeled in an arbitrary manner as $\{\alpha_1, \dots, \alpha_n\} = R_p^+$, $n = \text{rank } \mathfrak{g}$. Then there exist weights $\omega_i \in \mathfrak{h}^*$, $1 \leq i \leq n$, such that $\omega_i(H_{\alpha_j}) = \delta_{ij}$. These weights are called *fundamental weights*. Each highest weight can be written in a unique way as linear combination $\alpha = a_1\omega_1 + \dots + a_n\omega_n$, where all $a_i \in \mathbb{Z}_+$. Thus, often the notation $\Gamma_\alpha = \Gamma_{a_1\omega_1 + \dots + a_n\omega_n} = \Gamma_{a_1, \dots, a_n}$ is used.

DYNKIN DIAGRAMS

If $\text{rank } \mathfrak{g} > 2$, it is not very well possible to explicitly draw weight diagrams as we did for $\mathfrak{su}(3)$. Fortunately, there is a much more efficient way to graphically denote representations, which has been developed mainly by Dynkin. I will sketch here briefly, how all (semi-)simple Lie algebras can easily be classified with the help of a graphical notation, the so-called Dynkin diagrams, which encodes all the information on the Lie algebra. If one adds, in addition, the numbers a_1, \dots, a_n , $a_i = g(\alpha, \alpha_i)$, then the diagram also encodes all the information about the representations Γ_α , where I use the notation from [IIX].

Root systems. Let \mathfrak{g} be a semi-simple Lie algebra, \mathfrak{h} its Cartan subalgebra, g its Killing form, etc. The Euclidian space $\mathbb{E} = \text{span}_{\mathbb{R}} R$ is a real subvectorspace of \mathfrak{h}^* , on which g is positive definite. To characterize a Lie algebra, it suffices to classify the possible root systems $R \subset \mathbb{E}$ up to rotations und scalar multiplicationen. A root system has the properties:

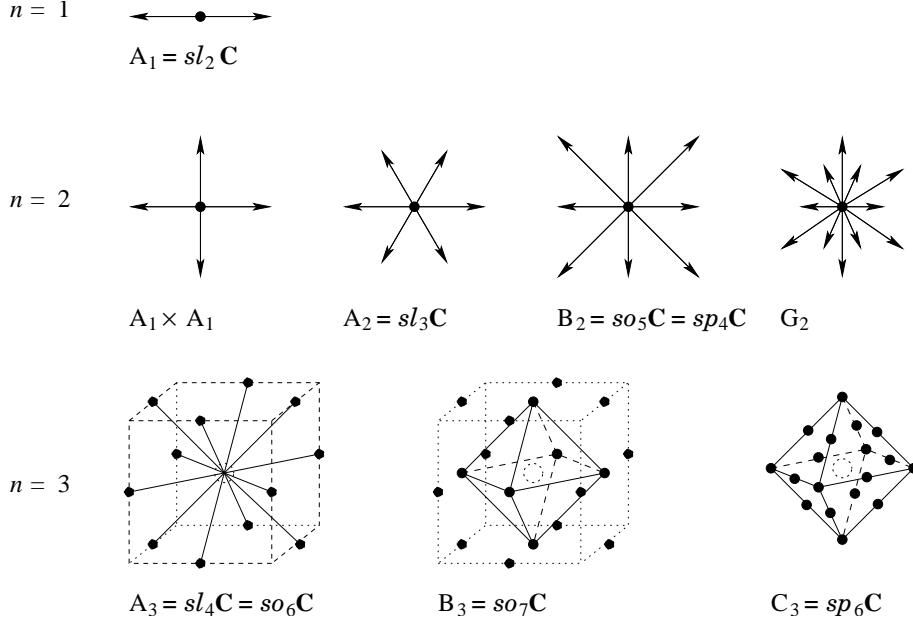
- [i] $|R| < \infty$, $\text{span}_{\mathbb{R}} R = \mathbb{E}$;
- [ii] $\alpha \in R \implies -\alpha \in R$, and more strictly $\alpha \in R \implies R \cap \{\mathbb{R}\alpha\} = \{\alpha, -\alpha\}$;
- [iii] $\alpha \in R \implies W_\alpha : R \rightarrow R$ with W_α the reflection in the α^\perp -plane;
- [iv] $\alpha, \beta \in R \implies \eta_{\beta\alpha} = \beta(H_\alpha) \in \mathbb{Z}$. The quantity $\eta_{\beta\alpha}$ and the Weyl reflection W_α can be expressed via the Killing form,

$$\eta_{\beta\alpha} = 2 \frac{g(\beta, \alpha)}{g(\alpha, \alpha)}, \quad W_\alpha(\beta) = \beta - \eta_{\beta\alpha} \alpha.$$

Condition [iv] is very restrictive, since it restricts the angle θ between to roots α, β to a very few possibilities. With $\cos \theta = g(\beta, \alpha) / \sqrt{g(\alpha, \alpha)g(\beta, \beta)}$, it follows that $\eta_{\beta\alpha} = 2\sqrt{g(\beta, \beta)/g(\alpha, \alpha)} \cos \theta \in \mathbb{Z}$, thus $4\cos^2 \theta = \eta_{\alpha\beta}\eta_{\beta\alpha} \in \mathbb{Z}$. This leaves only the possibilities $4\cos^2 \theta \in \{0, 1, 2, 3, 4\}$, where the last case $4\cos^2 \theta = 4$ occurs only in the trivial setting $\beta = \pm\alpha$. Without loss of generality one can assume that $g(\beta, \beta) \geq g(\alpha, \alpha)$, or $|\eta_{\beta\alpha}| \geq |\eta_{\alpha\beta}|$, respectively. This leads to the following table of non-trivial possibilities:

$4\cos^2 \theta$	3	2	1	0	1	2	3
$\cos \theta$	$\sqrt{3}/2$	$\sqrt{2}/2$	1/2	0	$-1/2$	$-\sqrt{2}/2$	$-\sqrt{3}/2$
θ	$\pi/6$	$\pi/4$	$\pi/3$	$\pi/2$	$2\pi/3$	$3\pi/4$	$5\pi/6$
$\eta_{\beta\alpha}$	3	2	1	0	-1	-2	-3
$\eta_{\alpha\beta}$	1	1	1	0	-1	-1	-1
$\sqrt{\frac{g(\beta, \beta)}{g(\alpha, \alpha)}}$	$\sqrt{3}$	$\sqrt{2}$	1	*	1	$\sqrt{2}$	$\sqrt{3}$

Let now $n = \dim_{\mathbb{R}}\mathbb{E} = \dim_{\mathbb{C}}\mathfrak{h} = \text{rank}g$. Below, all root systems for $1 \leq n \leq 3$ are sketched:



With a suitable but otherwise arbitrary semi-ordering $\ell : \mathbb{E} \rightarrow \mathbb{R}$ we divide the roots into two halves, $R = R^+ \cup R^-$. The positive simple roots for the classical Lie algebras are given in terms of the basic weights L_i as follows:

$$R_p^+ = \begin{cases} \{L_i - L_{i+1} : i = 1, \dots, n\} & \text{for } \mathfrak{sl}(n+1, \mathbb{C}) = A_n, \\ \{L_i - L_{i+1} : i = 1, \dots, n-1\} \cup \{L_n\} & \text{for } \mathfrak{so}(2n+1, \mathbb{C}) = B_n, \\ \{L_i - L_{i+1} : i = 1, \dots, n-1\} \cup \{2L_n\} & \text{for } \mathfrak{sp}(2n, \mathbb{C}) = C_n, \\ \{L_i - L_{i+1} : i = 1, \dots, n-1\} \cup \{L_{n-1} + L_n\} & \text{for } \mathfrak{so}(2n, \mathbb{C}) = D_n. \end{cases}$$

The properties [i] to [iv] have immediate consequences, which must be satisfied by root systems R .

[v] For all $\alpha, \beta \in R$, $\beta \neq \pm\alpha$, the whole string $\{\beta - p\alpha, \beta - (p-1)\alpha, \dots, \beta - \alpha, \beta, \beta + \alpha, \beta + 2\alpha, \dots, \beta + q\alpha\} \subset R$ must belong to the root system. Since we must also have that $W_\alpha(\beta + q\alpha) = \beta - p\alpha = (\beta - \eta_{\beta\alpha}\alpha) - q\alpha$, it follows that $p = \eta_{\beta\alpha} + q$. This yields the restriction $p + q \leq 3$, $p - q = \eta_{\beta\alpha}$.

[vi] For all $\alpha, \beta \in R$, $\beta \neq \pm\alpha$, it follows with the help of the Killing form that

$$\begin{aligned} g(\beta, \alpha) > 0 &\implies \alpha - \beta \in R, \\ g(\beta, \alpha) < 0 &\implies \alpha + \beta \in R, \\ g(\beta, \alpha) = 0 &\implies \alpha - \beta, \alpha + \beta \text{ either both } \in R \text{ or both } \notin R; \end{aligned}$$

[vii] If $\alpha \neq \beta \in R_p^+$ are simple positive roots, then $\alpha - \beta \notin R$, $\beta - \alpha \notin R$ cannot be roots;

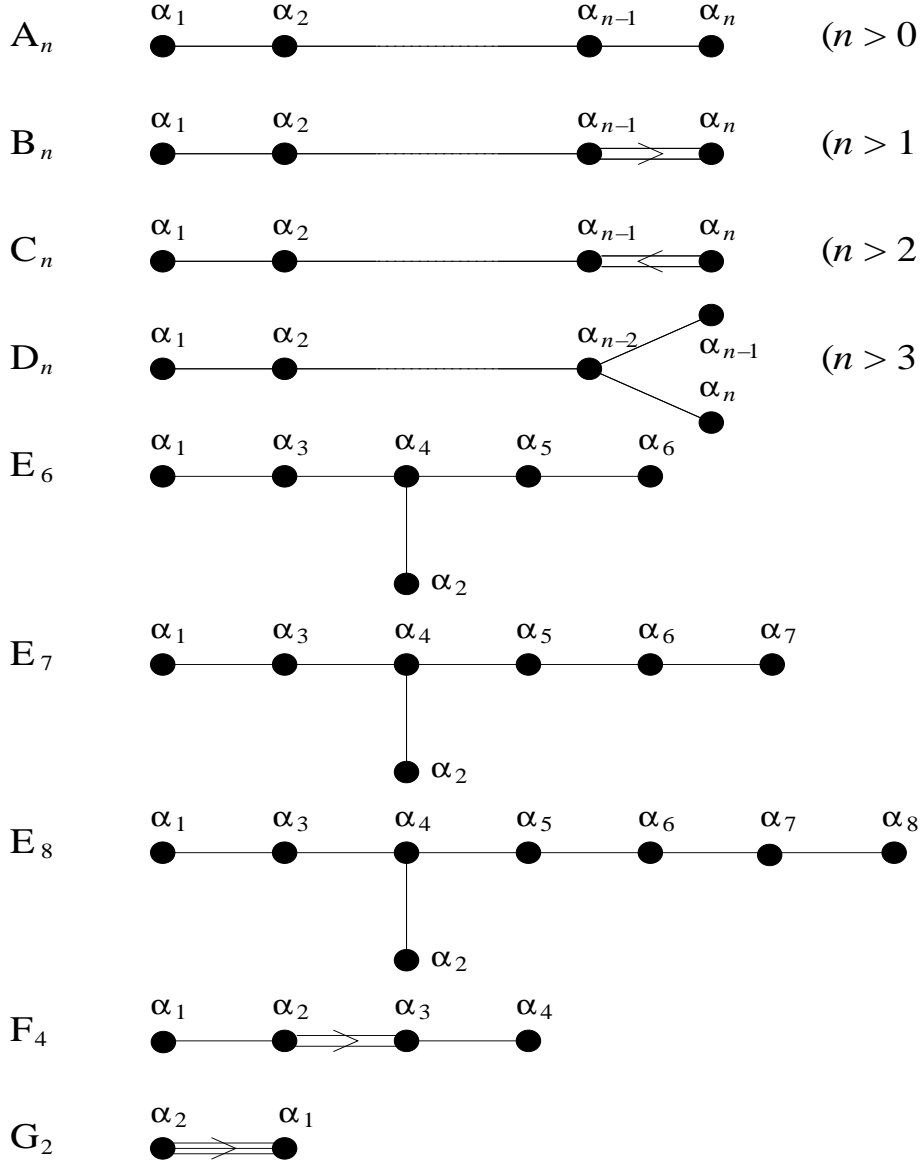
[iix] If $\alpha \neq \beta \in R_p^+$ are simple positive roots, then the angle between them cannot be sharp, i.e. $\cos \theta = \sqrt{g(\alpha, \alpha)/g(\beta, \beta)\eta_{\beta\alpha}}/2 \leq 0$;

[ix] The simple positive roots are linearly independent;

[x] $|R_p^+| = n = \text{rank}g$, such that each $\alpha \in R^+$ has a unique decomposition $\alpha = a_1\alpha_1 + \dots + a_n\alpha_n$, where $\alpha_i \in R_p^+$ und $a_i \in \mathbb{Z}_+$.

Dynkin diagrams. Label the positive simple roots in an arbitrary manner, $R_p^+ = \{\alpha_1, \dots, \alpha_n\}$. It follows from [iix] that $\alpha_i, \alpha_j \in R_p^+$ can only form from the angles $\theta \in \{\pi/2, 2\pi/3, 3\pi/4, 5\pi/6\}$. Correspondingly, $\eta_{\alpha_i, \alpha_j}$ takes the values $\{0, -1, -2, -3\}$. Draw a graph with one node for each α_i , and with exactly $\eta_{\alpha_i, \alpha_j}\eta_{\alpha_j, \alpha_i}$ lines linking the nodes α_i and α_j . To make it even more beautiful, draw an arrow on the linking lines from the longer root to the shorter one, if $g(\alpha_i, \alpha_i) \neq g(\alpha_j, \alpha_j)$. One can prove that only the connected graphs listed below correspond to irreducible root systems which satisfy the properties [i] to [iv] (and therefore also [v] to [x]). These are the *Dynkin diagrams* of the semi-simple Lie algebras. This classifies all semisimple Lie algebras! Furthermore, any irrep $\Gamma_\alpha = \Gamma_{a_1, a_2, \dots, a_n}$ can be completely characterized by a Dynkin diagram by simply denoting the number a_i near the node α_i . These coefficients a_i were obtained by introducing the fundamental weights ω_i with $g(\omega_i, \alpha_j) = \delta_{ij}$, such that obviously $a_i = g(\alpha, \alpha_i)$. Indeed, any irrep, i.e. its weight diagram including all multiplicities, can be reconstructed from the Dynkin diagram of the underlying Lie algebra together with the weight coefficients a_i . The Dynkin diagram contains, for instance, all values of the so-called *Cartan matrix* $n_{i,j} \equiv \eta_{\alpha_i, \alpha_j}$. In the diagrams below, the labeling

goes from left to right following the lists for $R_p^+ = \{\alpha_1, \dots, \alpha_n\}$ given earlier in the text for the classical groups, and further below for the exceptional ones.



Finally, I make some comments regarding the restrictions concerning the minimal rank for Lie algebras in the series A, B, C, D . These restrictions avoid that the same graph appears multiple times in different series.

For $n = 1$ we find $B_1 = C_1 = A_1$, which corresponds to the isomorphies $\mathfrak{so}(3, \mathbb{C}) \cong \mathfrak{sp}(2, \mathbb{C}) \cong \mathfrak{sl}(2, \mathbb{C})$. All these Dynkin diagrams consist of just one single node. The case $D_1 = \mathfrak{so}(2, \mathbb{C})$ must be excluded, because this Lie algebra is not semi-simple.

For $n = 2$ we find $D_2 = A_1 \times A_1$ corresponding to the isomorphism $\mathfrak{so}(4, \mathbb{C}) \cong \mathfrak{sl}(2, \mathbb{C}) \times \mathfrak{sl}(2, \mathbb{C})$. The Dynkin diagrams consist out of two disjunct nodes without a joining line. Further, we find $C_2 = B_2$ corresponding to the isomorphism $\mathfrak{sp}(4, \mathbb{C}) \cong \mathfrak{so}(5, \mathbb{C})$. The associated Dynkin diagrams are equal, since the direction of the arrow on the linking line is irrelevant in the case of just two nodes.

For $n = 3$ we finally find $D_3 = A_3$ corresponding to the isomorphism $\mathfrak{so}(6, \mathbb{C}) \cong \mathfrak{sl}(4, \mathbb{C})$.

If one wishes, one can successively eliminate nodes from right to left to formally obtain the equivalences $E_5 = D_5$, $E_4 = A_4$, $E_3 = A_2 \times A_1$, $E_2 = A_1 \times A_1$ and $E_1 = A_1$.

The root systems for the exceptional Lie algebras read as follows:

$$R_p^+ = \begin{cases} \{L_1, -\frac{3}{2}L_1 + \frac{\sqrt{3}}{2}L_2\} & \text{für } G_2, \\ \{L_2 - L_3, L_3 - L_4, L_4, \frac{1}{2}(L_1 - L_2 - L_3 - L_4)\} & \text{für } F_4, \\ \{\frac{1}{2}(L_1 - L_2 - L_3 - L_4 - L_5 + \sqrt{3}L_6), L_1 + L_2, \} \cup \{L_{i+1} - L_i : i = 1, \dots, 4\} & \text{für } E_6, \\ \{\frac{1}{2}(L_1 - L_2 - \dots - L_6 + \sqrt{2}L_7), L_1 + L_2\} \cup \{L_{i+1} - L_i : i = 1, \dots, 5\} & \text{für } E_7, \\ \{\frac{1}{2}(L_1 - L_2 - \dots - L_7 + L_8), L_1 + L_2\} \cup \{L_{i+1} - L_i : i = 1, \dots, 6\} & \text{für } E_8. \end{cases}$$